

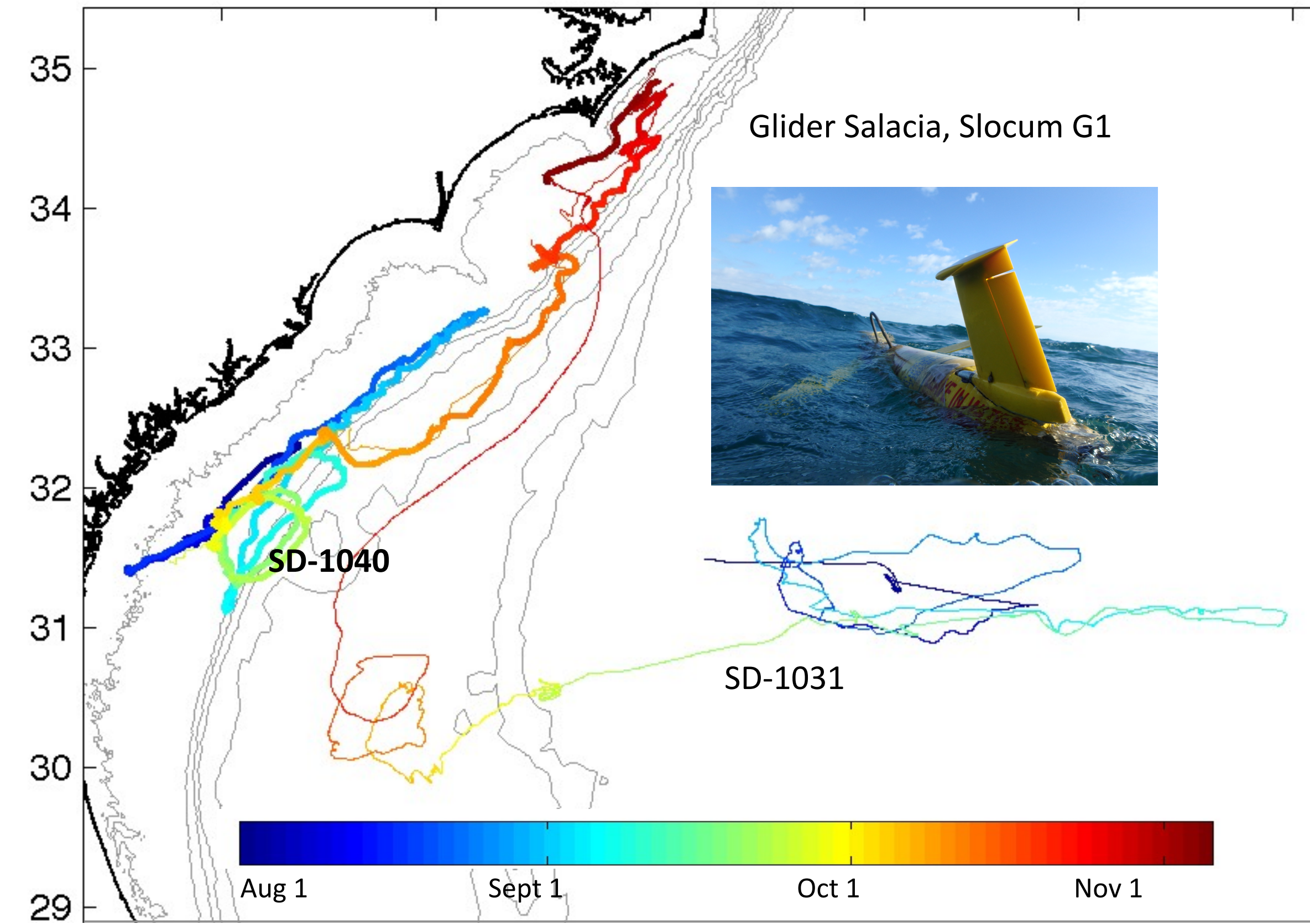
COORDINATED AUTONOMOUS SURFACE VEHICLE AND UNDERWATER GLIDER OPERATIONS IN THE GULF STREAM DURING HURRICANE SEASON 2021

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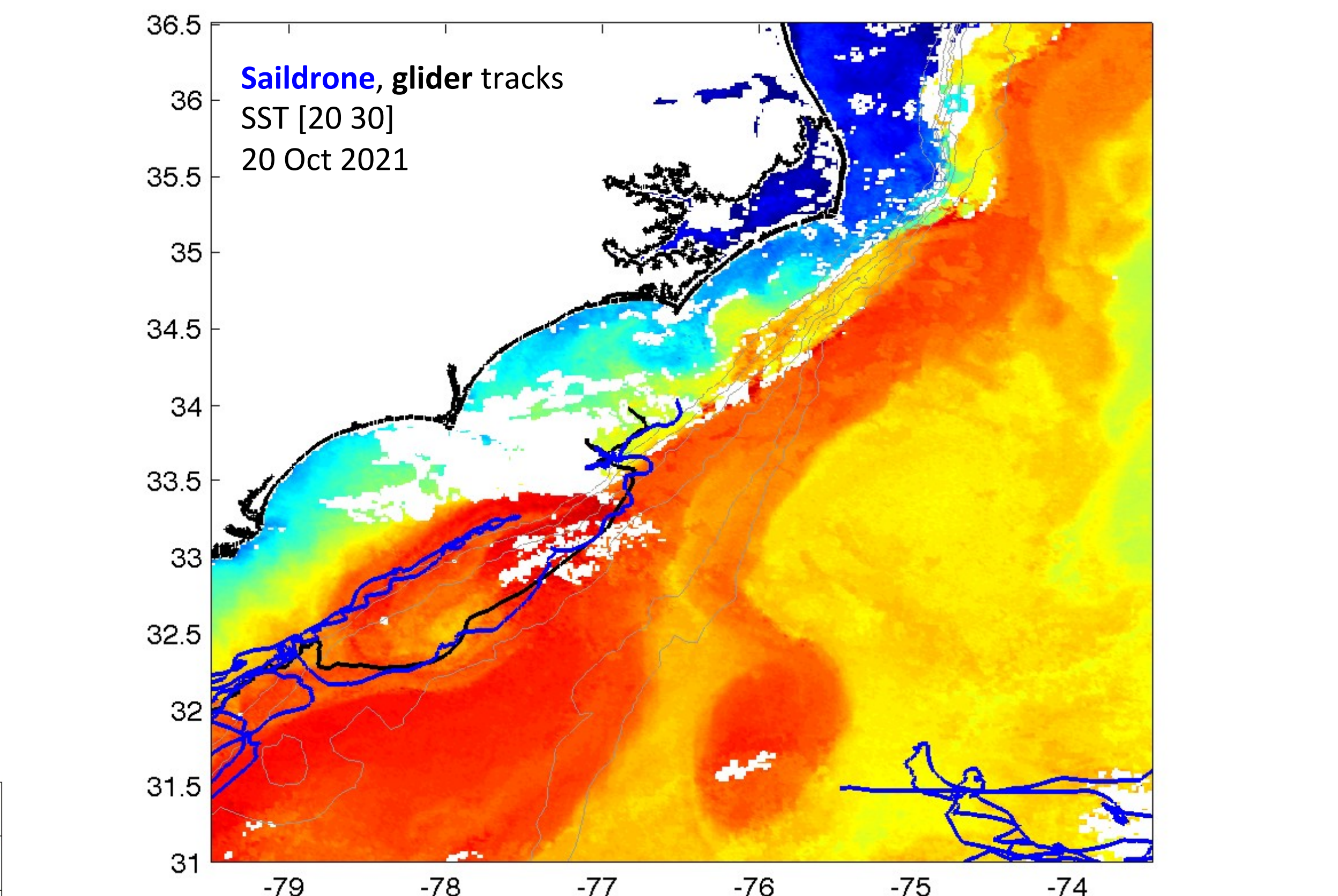
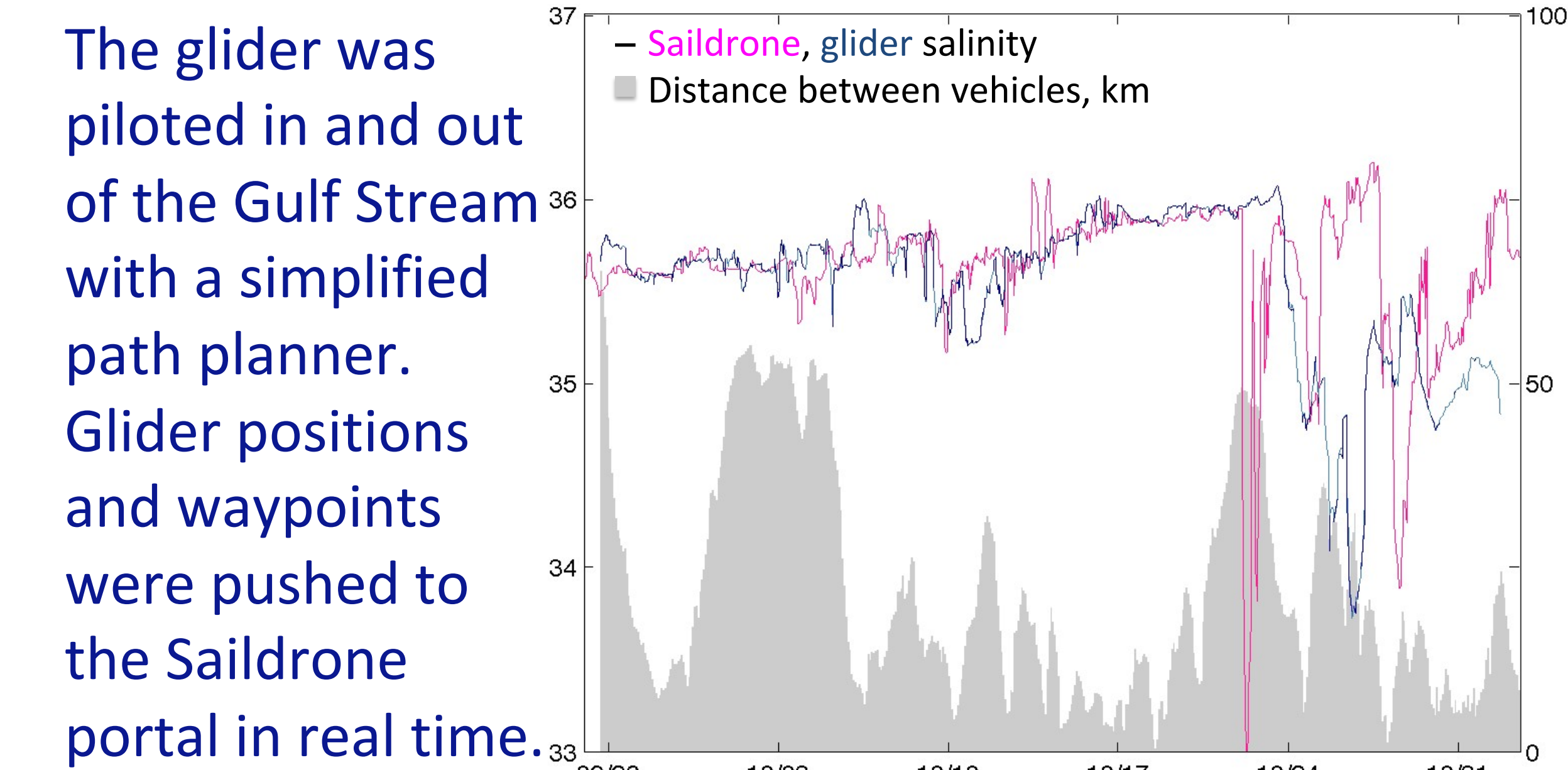
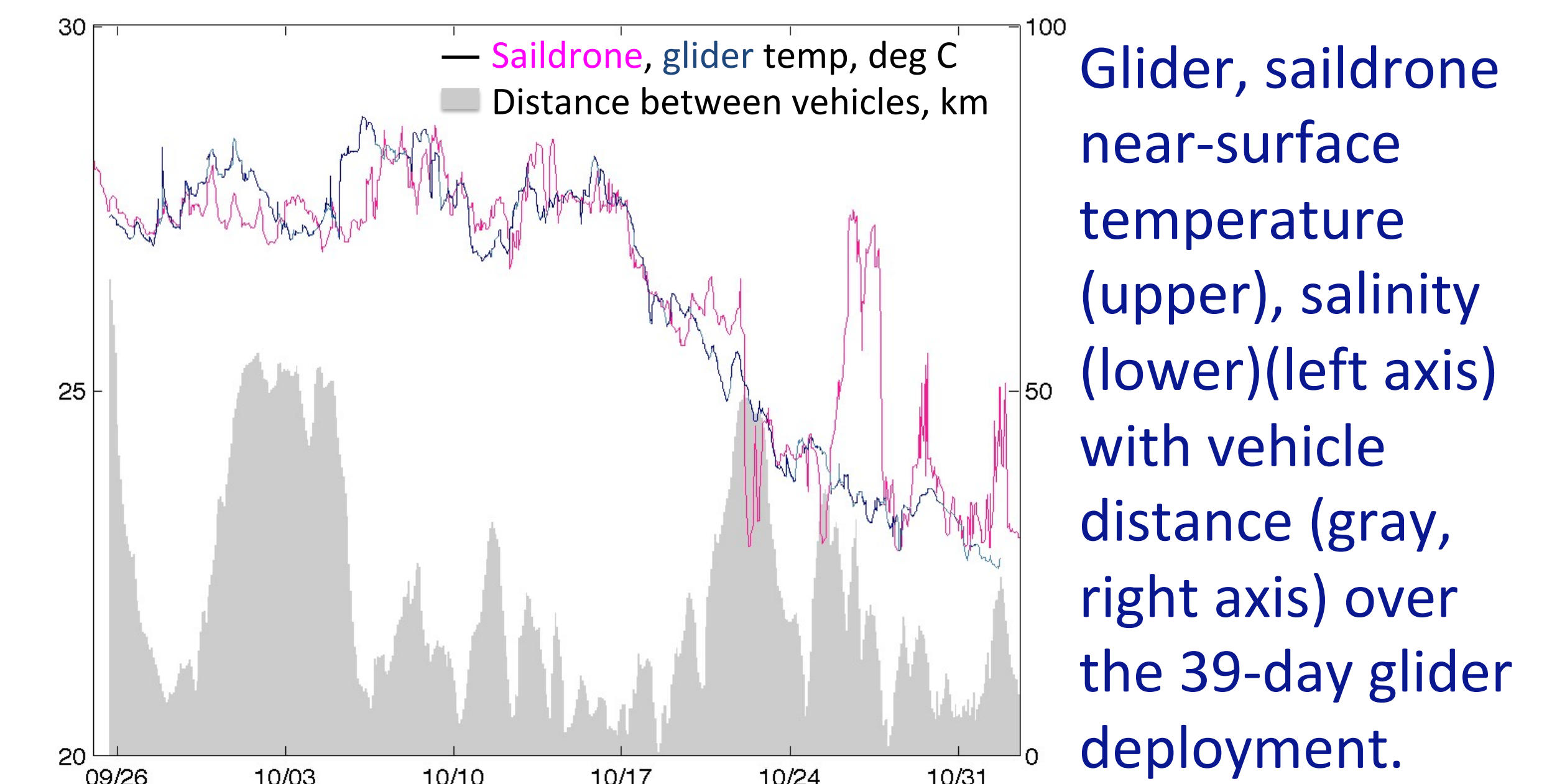
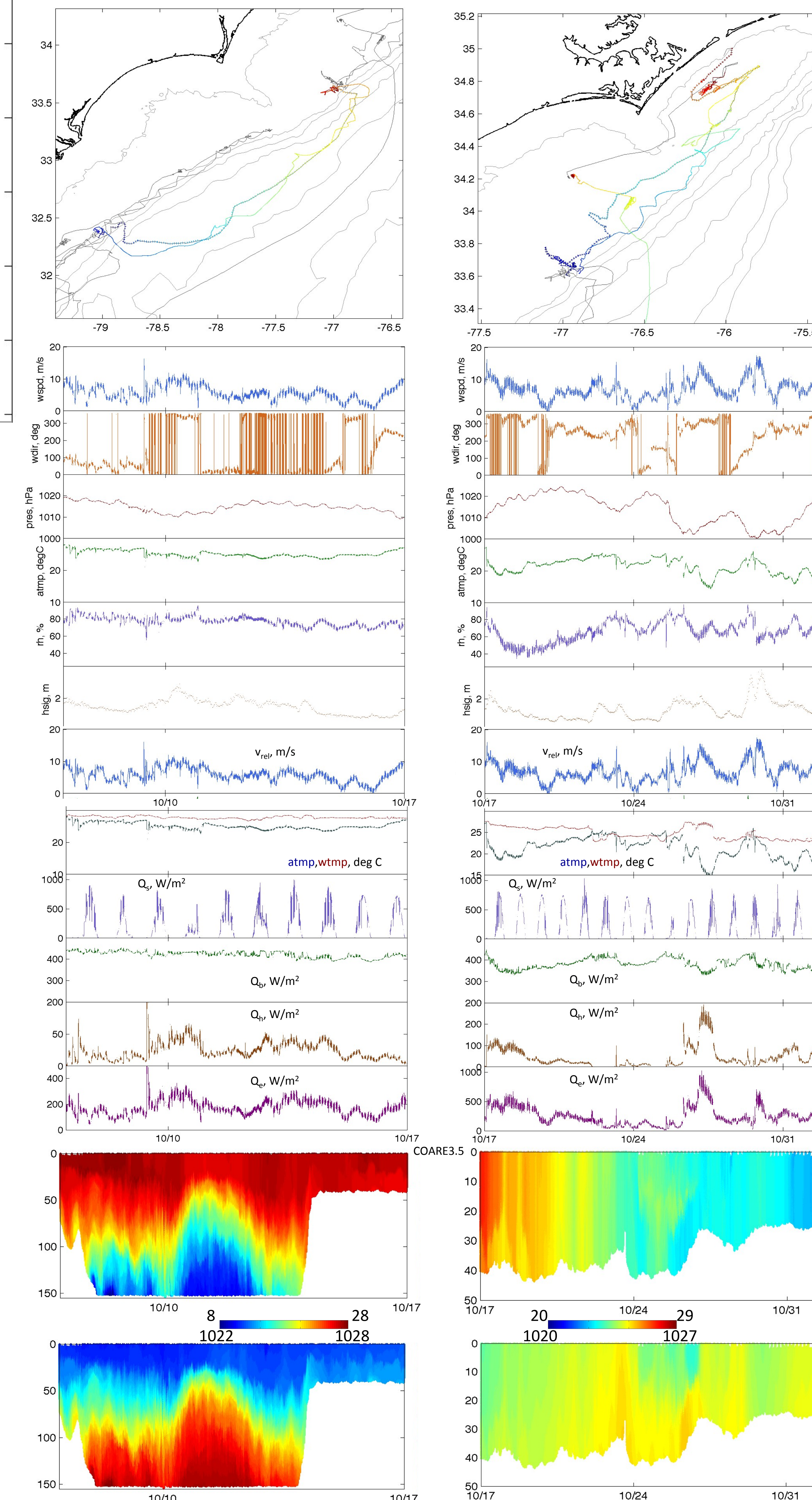
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Mission overview

During the Atlantic hurricane season, 5 experimental Saildrone uncrewed surface vehicles (USVs) measured near-surface meteorological and upper ocean data in areas of high tropical cyclone heat potential and storm incidence. Three were paired with underwater gliders, including two vehicles operating in and near the Gulf Stream.

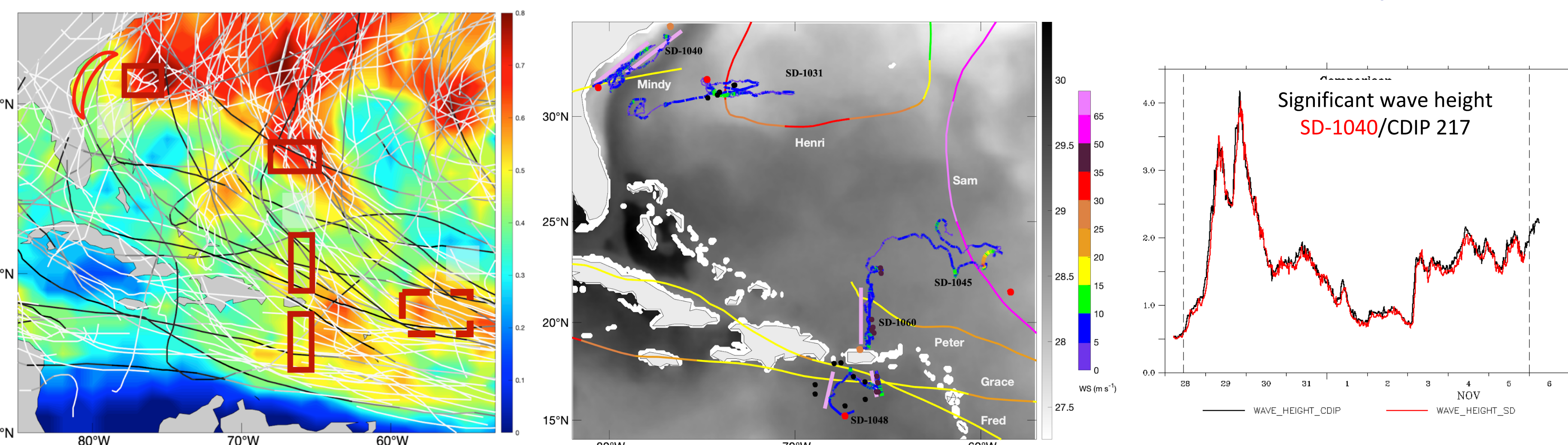
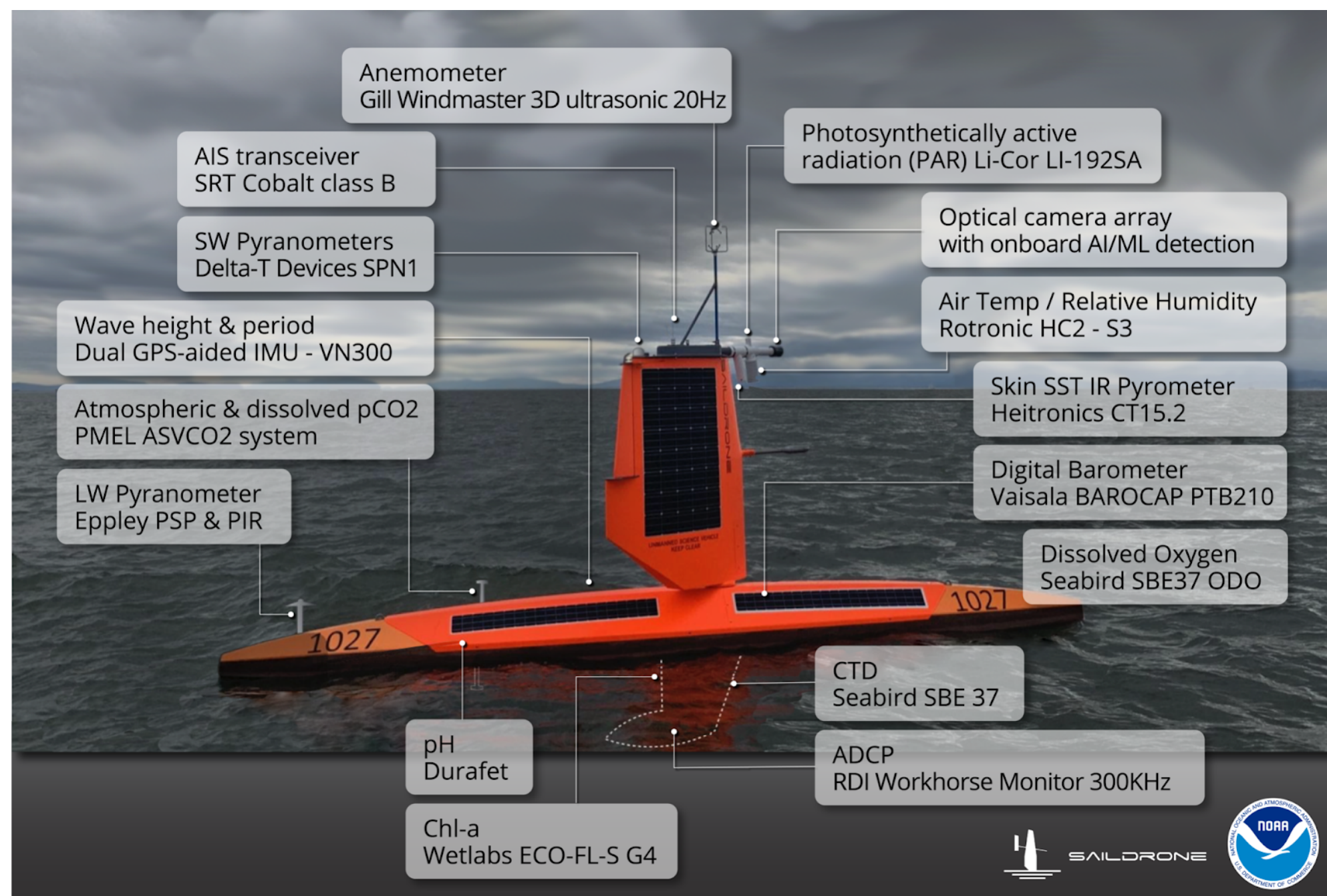


Paired glider-saildrone data



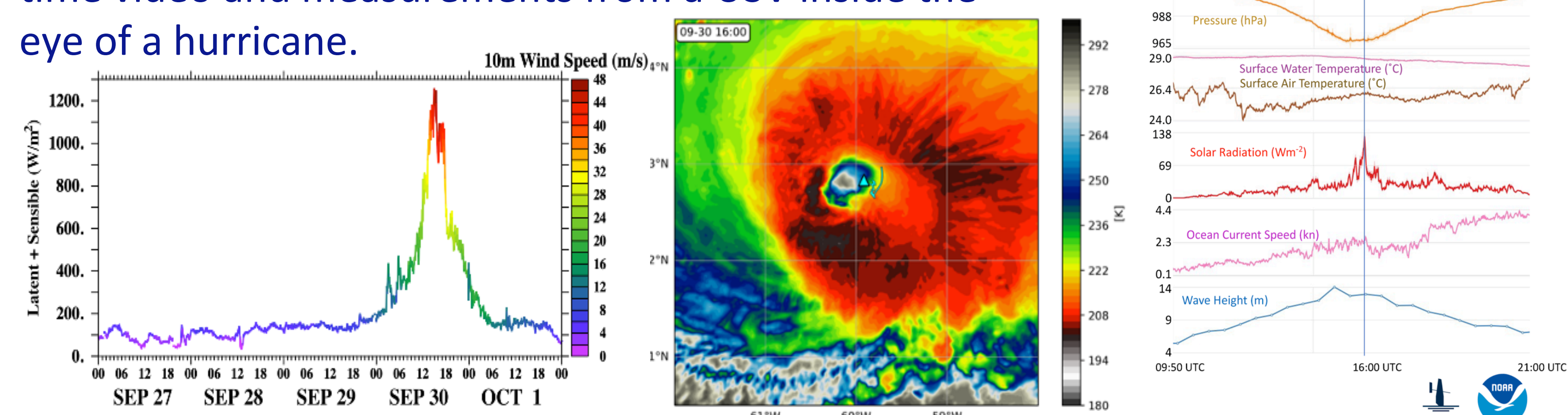
Cross-platform validation

With a modified wing to withstand hurricane-force winds, each saildrone was outfitted with meteorological and ocean sensors (left). During each ~100 day mission (August 1-November 5), the saildrones sampled near NDBC and CDIP buoys, as well as research vessels of opportunity, to cross-validate wind, wave, near-surface, and subsurface oceanographic data collected with traditional platforms.



Hurricane Sam

“Stormcatcher” SD-1045 was piloted to intercept Hurricane Sam, measuring 50+ m/s winds and providing the first real time video and measurements from a USV inside the eye of a hurricane.



Expanding autonomy

The 2021 field effort suggests that coordinated robotic surface and underwater vehicles can permit long endurance autonomous sampling of air-sea interaction in the Gulf Stream, where operational challenges motivate coordination through an intelligent, adaptive, and robust robotic network. Future work will involve modification of path planning software (GENIoS, with collaborator F. Zhang) to develop algorithms tailored to the constraints of saildrones and other USVs.