Predictability and non-normal dynamics in models

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Outline

- Explore predictability of AMOC in models, both simple and complex
- Describe predictability experiments with the MITgcm- Double Drake (DDR)
- Interpretation in terms of non-normal mode dynamics, and comparison of DDR with CM2.

Exploring predictability in models

- Long term observations of MOC are scarce and models display a wide range of MOC decadal variability - poorly understood
- Goal is to develop a model-independent, diagnostic measure of MOC predictability
- Begin by exploring a model of intermediate complexity: aqua-planet configuration of the MITgcm



Double Drake: "Perfect" Ensembles



- "perfect" ocean IC's, with perturbed atmospheres
- all variability occurs on the western boundary
- predictable for at least one 35 year cycle

Prognostic Potential Predictability $PPP(t) = 1 - \frac{\frac{1}{N(M-1)} \sum_{j=1}^{N} \sum_{i=1}^{M} [X_{ij}(t) - \overline{X}_{j}(t)]^{2}}{\sigma^{2}}$

$$PPP(t) > 1 - \frac{1}{F_{N(M-1),k-1}}$$



Double Drake: "Perfect" Ensembles ctd.



- I. Temperature dominates MOC variability, salinity has little effect
- 2. Sampling frequency: IC's in the ocean can be averaged over a fraction of an oscillation period (~1/4 cycle) without losing much predictability.
- 3. Both the upper 1km and deep ocean are important for determining the phase of the MOC
- 4. Even though the temperature anomalies form on the eastern boundary, and all the MOC variability occurs on the western boundary, perturbing S/T on either boundary does not significantly alter the phase of the MOC

Bowled Double Drake 600 years of simulation after 1500 year spinup



Bowled Double Drake: "Perfect" Ensembles







- ensembles track the MOC better when starting at a maximum or minimum (lower row)
- MOC variability still occurs on the western boundary
- high ensemble variance and low control variance implies low PPP.
- These are worst case ensembles since they assume no knowledge of the atmospheric state, which is likely the main forcing

 A change from a flat to bowled bathymetry suppresses baroclinic instability near the eastern boundary, switching from an internally forced, highly predictable MOC to a stochastically forced, less predictable MOC.

 How do non-normal dynamics change when we switch to bowled bathymetry?

Non-normal dynamics

• For a stable linear system dP/dt = AP, rapid, transient error amplification can occur (if the matrix A is non-normal) when decaying non-orthogonal eigenmodes interact.



- Reduced space approach (Tziperman et al. 2008): assuming that the evolution of the principal components of the non-dimensionalized S and T fields is linear, a propagator matrix B can be obtained.
- Given the propagator matrix, the optimal initial conditions of the principal components are obtained from a generalized eigenvalue problem subject to either an energy norm or an overturning norm.
- The propagator matrix then predicts the rate of optimal error amplification.

Non-normal dynamics in the Double Drake



Double Drake versus Bowled Double Drake



Comparison with CM2.I



Tziperman et al. (2008)

Conclusions

- MOC in the Double Drake (DDR) is very predictable, due to internal instability which produces theta anomalies near eastern boundary (salinity not important)
- DDR with bowled bathymetry appears to be stochastically driven by the atmosphere, is harder to predict, though perhaps more realistic
- Optimal IC's in the DDR agree with composite high MOC theta
- Rates of optimal amplification are very similar between CM2.1 and DDR