

An Integration and Assessment of Nonstationary Storm Surge Statistical Behavior



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Introduction

- **Storm surge** is a key driver of uncertainty in future coastal hazards¹
- We consider two key deep uncertainties in future storm surge hazard:
 - **Model choice** for storm surge²
 - **Potential nonstationarity** in storm surge frequency and intensity
- So we ask:
 1. What are projections of future storm surge hazard?
 2. What are the impacts on these projections from deep uncertainty in storm surge model choice and nonstationarity?
- We use **Norfolk, VA** as a case study and demonstrate the use of **Bayesian model averaging** (BMA) as a tool to characterize the deep uncertainty surrounding model structural choice and nonstationarity.

Methods

- We use tide gauge data from Sewells Point (1928-2016) and consider four possible **covariates** of storm surge behavior:
 - (1) **time**³, (2) global mean **temperature**^{3,4,5}, (3) global mean **sea level**^{6,7}, and (4) winter mean North Atlantic Oscillation (**NAO**) **index**^{2,8}.
- For each candidate covariate ($\phi(t)$), we fit a statistical model in which a **Poisson process** (PP) governs the arrival of events whose sea level exceeds the 99th percentile of detrended daily mean sea levels, and these exceedances follow a **generalized Pareto distribution** (GPD).
- Potential nonstationarity in model parameters ($\theta \in \{\lambda, \sigma, \xi\}$) following *Grinsted et al.*³:

Parameters:	λ : Poisson rate	$\lambda(t) = \lambda_0 + \lambda_1 \phi(t)$
	σ : GPD scale (width)	$\sigma(t) = \exp[\sigma_0 + \sigma_1 \phi(t)]$
	ξ : GPD shape (tail)	$\xi(t) = \xi_0 + \xi_1 \phi(t)$

- For each candidate covariate, in addition to the fully nonstationary model above (**NS3**), we consider a stationary model (**ST**) and two other potentially nonstationary models:

$$\text{ST} : \lambda_1 = \sigma_1 = \xi_1 = 0, \quad \text{NS1} : \sigma_1 = \xi_1 = 0, \quad \text{NS2} : \xi_1 = 0$$

- We estimate parameter posterior distributions using Markov chain Monte Carlo, and compute **Bayesian model averaging** weights for each model (M_k), given the tide gauge data (\mathbf{x}):

$$p(M_k|\mathbf{x}) = \frac{p(\mathbf{x}|M_k)p(M_k)}{\sum_{j=1}^m p(\mathbf{x}|M_j)p(M_j)}$$

- We integrate return level estimates in year y_i ($RL(y_i)$) across model structures using the BMA weights $p(M_k|\mathbf{x})$:

$$RL(y_i|\mathbf{x}) = \sum_{k=1}^m RL(y_i|M_k) p(M_k|\mathbf{x})$$

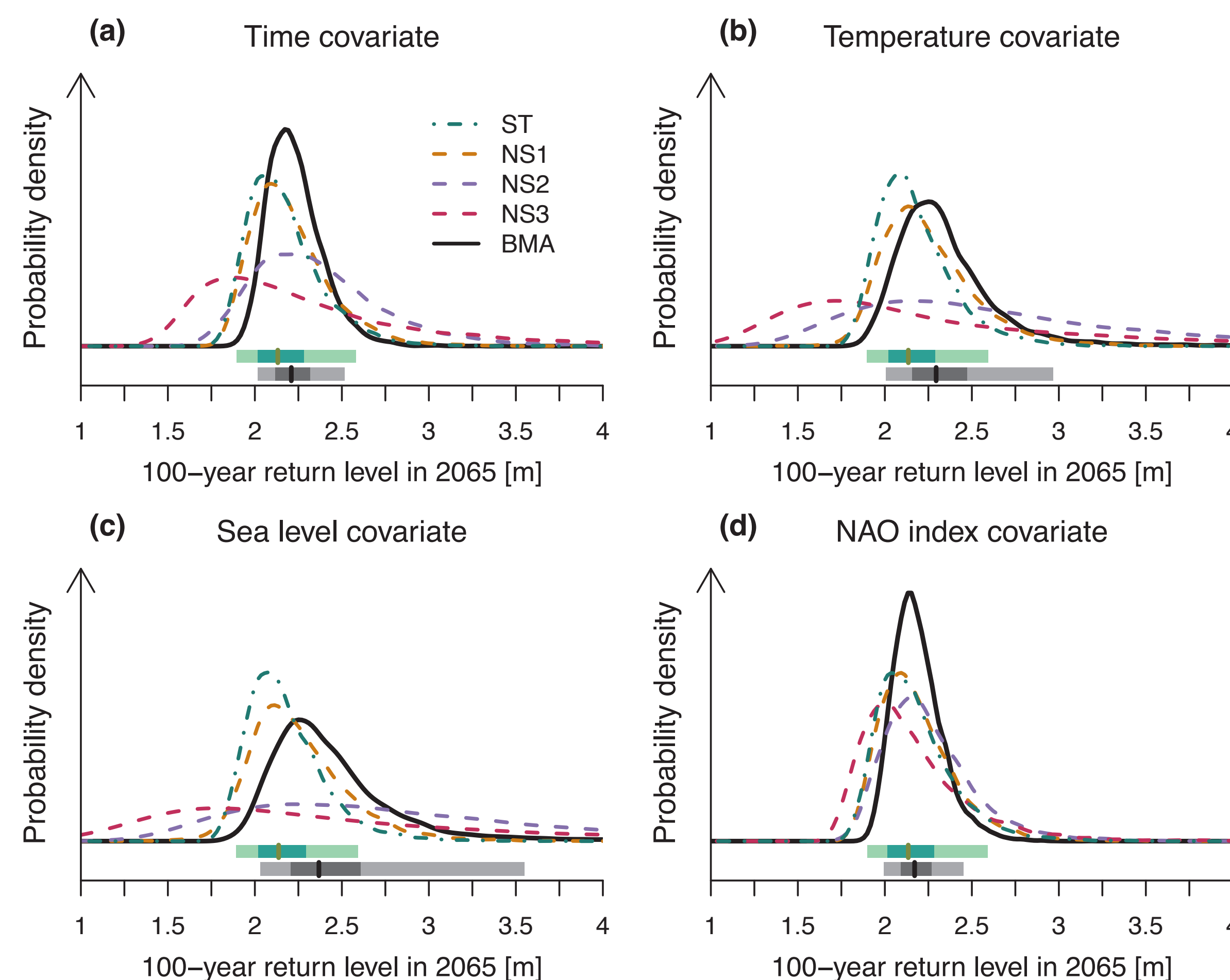
Results

- **Key result #1:** For any given covariate structure, about half the model weight is associated with nonstationary statistical models.

BMA weights:

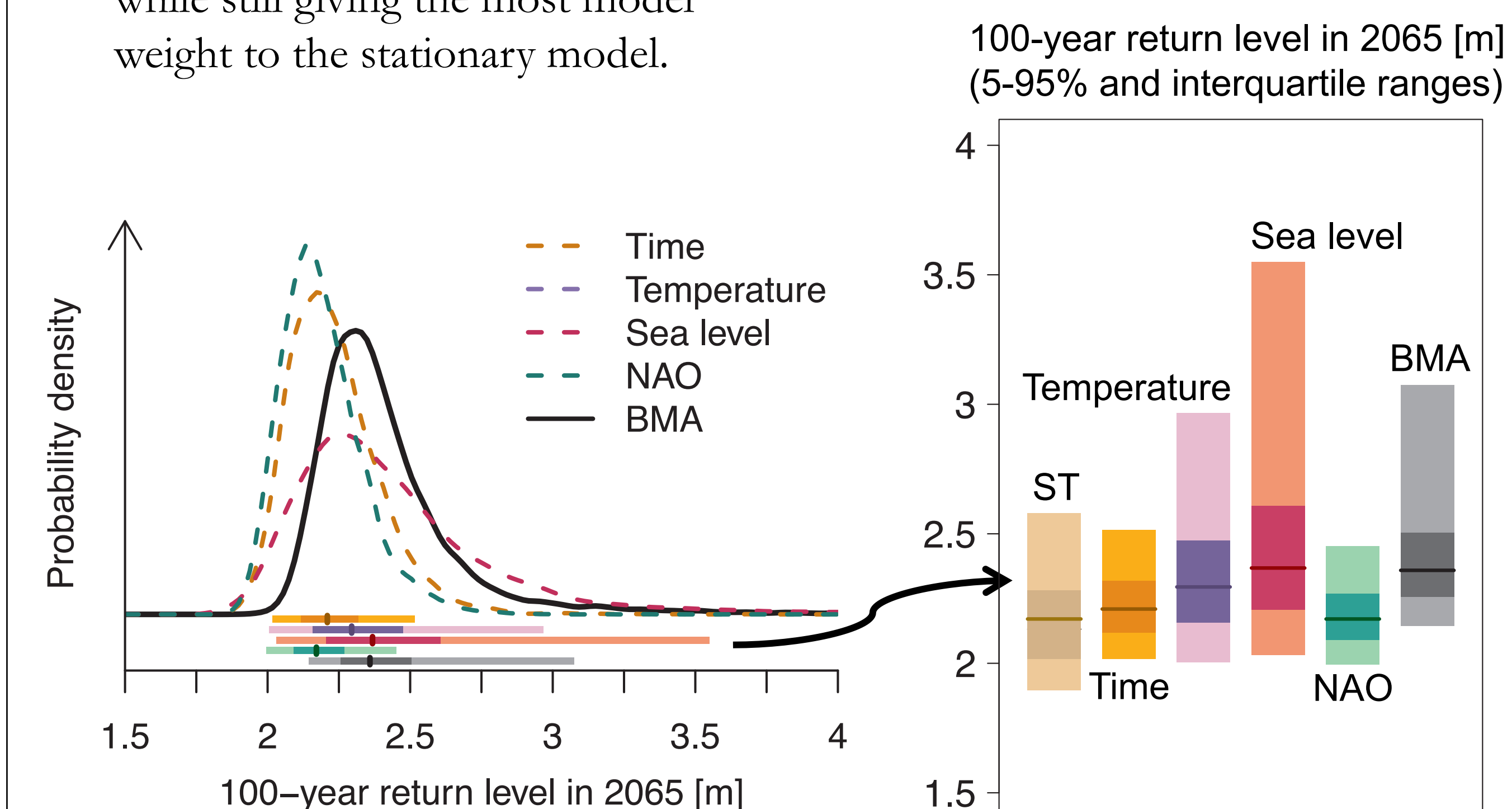
Covariate / Model	ST	NS1 (λ varying)	NS2 (λ, σ varying)	NS3 (λ, σ, ξ varying)
Time	0.52	0.25	0.17	0.06
Temperature	0.55	0.24	0.15	0.06
Sea level	0.55	0.24	0.16	0.06
NOA index	0.55	0.24	0.16	0.05

- **Key result #2:** Bayesian model averaging successfully combines flood hazard projections, across uncertain model structures.
 - The additional information (covariates of storm surge nonstationarity) raise the upper tail of projected flood hazard.



In a final experiment, we combine using BMA a stationary model with all four candidate covariates' three nonstationary models (total of 13 model structures).

- **Key result #3:** Accounting for nonstationarity and uncertain model structure increases the estimated 100-year return level by up to 23 cm, while still giving the most model weight to the stationary model.



Discussion

- Bayesian model averaging (BMA) is a useful tool to combine model predictions when there is disagreement over which model to use.
- We used BMA to address uncertainty in which covariate (if any!) to use, and uncertainty in which (non)stationarity structure to use.
 - The degree to which we believe the nonstationary models/different covariates is **informed by the data**.
- Provides guidance on how best to incorporate nonstationary processes into flood hazard estimates, and a framework to integrate other locally important climate variables, to better inform coastal risk management practices.

References

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