# Energetically consistent, resolution aware, parameterization of ocean mesoscale eddies

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#### The Problem

- Model resolutions between  $\sim 1-1/8$ th degree occupy awkward "grey zone" where mesoscale "eddies" are (barely) permitted but not properly resolved
- Challenging to leverage this resolution regime, arguably because existing parameterizations are overly dissipative for eddy permitting simulations.
- Current "state of the art" is to treat models as either "eddying" or "non-eddying" in a binary manner (potentially switching within domain - e.g. Hallberg 2013)
- Noting that there exists a continuum of (transient and standing) eddy scales, can we do better than that?

#### Energetics in Ocean models



#### Energetics in Ocean models "Backscatter" (e.g. Jansen et al. 2015)



#### Energetics in Ocean models "Energy budget-based GM" (e.g. Eden and Greatbatch 2008)



# Energetics in Ocean models Putting it all together



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#### see also: Bachman 2019, Ocean modelling



$$\partial_t e = \dot{e}_{GM} + \dot{e}_{\nu_4} - \dot{e}_{\nu_2} - \dot{e}_{diss} + \frac{1}{H} \nabla$$

![](_page_7_Picture_3.jpeg)

![](_page_8_Figure_1.jpeg)

$$\partial_t e = \dot{e}_{GM} + \dot{e}_{\nu_4} - \dot{e}_{\nu_2} - \dot{e}_{diss} + \frac{1}{H} \nabla$$

![](_page_8_Picture_3.jpeg)

![](_page_8_Picture_4.jpeg)

![](_page_9_Figure_1.jpeg)

$$\partial_t e = \dot{e}_{GM} + \dot{e}_{\nu_4} - \dot{e}_{\nu_2} - \dot{e}_{diss} + \frac{1}{H} \nabla$$

$$\begin{aligned}
\nu_{4} &= (c_{smag} | D | + \tau_{\nu_{4}}^{-1}) \Delta^{4} \\
K_{GM} &= -\nu_{2} = \alpha \sqrt{2e} L_{mix} R(\Delta A) \\
L_{mix} &= \min(\Delta, L_{\beta^{*}}) \\
\cdot (H\mathbf{F}_{e}) \\
R(\Delta k_{d}) &= \left[1 + \left(\frac{\Delta k_{d}}{\pi}\right)^{-2}\right]
\end{aligned}$$

![](_page_9_Picture_4.jpeg)

![](_page_9_Picture_5.jpeg)

![](_page_10_Figure_1.jpeg)

$$\partial_t e = \dot{e}_{GM} + \dot{e}_{\nu_4} - \dot{e}_{\nu_2} - \dot{e}_{diss} + \frac{1}{H} \nabla$$

$$\dot{e}_{diss} = -c_d \sqrt{(e + \mathbf{u}_{bot}^2 + U_{bg}^2)} e$$

$$\begin{aligned}
\nu_{4} &= (c_{smag} | D | + \tau_{\nu_{4}}^{-1}) \Delta^{4} \\
K_{GM} &= -\nu_{2} = \alpha \sqrt{2e} L_{mix} R(\Delta A) \\
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R(\Delta k_{d}) &= \left[1 + \left(\frac{\Delta k_{d}}{\pi}\right)^{-2}\right]
\end{aligned}$$

![](_page_10_Picture_5.jpeg)

![](_page_10_Picture_6.jpeg)

#### Neverland

![](_page_11_Figure_1.jpeg)

• MOM6

• 6 isopycnal layers

• fully adiabatic

#### Neverland A high resolution reference solution

![](_page_12_Figure_1.jpeg)

#### Testing parameterizations

• We will here consider three different parameterizations: MEKE GM + Backscatter: k

> $K_{GM} = const. = 1000 \, m^2 s^{-1}$ Constant GM:

- A "resolution aware" version of Visbeck (1997): K
- In all cases one parameter is tuned to match mean-state APE from high-res simulation at  $1/2^{\circ}$  resolution!

$$K_{GM} = -\nu_2 = \alpha \sqrt{2e} L_{mix} R(\Delta k_d)$$
 with  $\alpha = 0.16$ 

$$K_{GM} = \gamma s N \Delta^2$$
 with  $\gamma = 1.1$ 

#### Results Constant GM at 1/2 degree resolution

![](_page_14_Figure_1.jpeg)

#### Results "Visbeck" at 1/2 degree resolution

![](_page_15_Figure_1.jpeg)

#### Results Energy-budget based GM + backscatter at 1/2 degree resolution

![](_page_16_Figure_1.jpeg)

#### Resolved and sub-grid KE as a function of resolution

![](_page_17_Figure_1.jpeg)

# Mean flow as a function of resolution 1) Metrics

Three metrics are here considered to quantitatively test mean state representation:

 $APE = \sum$ 1) Mean-state APE: n 2) Weighted interface height error:  $\epsilon^2 = \frac{1}{A} \sum_{A=1}^{A} \sum_$  $T_{ACC} = \sum_{n=1}^{\infty} \left| (\overline{vh})_n dx \right|$ 3) ACC transport:

$$\iint g'_n \bar{\eta}_n^2 dx dy \qquad (\text{used to "tune" parameterization} - \mathbf{ff}$$

$$\sum_{n} \iint g'_n (\bar{\eta}_n - \bar{\eta}_{n1/16})^2 dx dy$$

$$\int (vh)_n dt$$

![](_page_18_Picture_6.jpeg)

# Mean flow as a function of resolution 2) Results

![](_page_19_Figure_1.jpeg)

# Conclusions

- the resolved flow.
- zone":
- a) More energetic flow with improved internal variability b) Smooth connection between the non-eddying and eddy-resolving regimes, with
- Important questions (and room for improvement) remain, including: a) Vertical structure of eddy energy and fluxes b) Transport of (sub-grid) eddy energy c) Sub-grid dissipation?!

• Energy budget based mesoscale eddy closures can be useful if we account for energy "backscatter" to

• Including backscatter can lead to significant improvements, particularly in barely eddy permitting "grey

c) Mean flow properties as good or better than GM (at relatively coarse res) or no GM (at higher res)

![](_page_20_Figure_11.jpeg)

![](_page_20_Picture_12.jpeg)

#### Variance spectra

![](_page_21_Figure_1.jpeg)

#### Kinetic energy spectra

![](_page_22_Figure_1.jpeg)

# Mean Flow SSH

![](_page_23_Figure_1.jpeg)

![](_page_23_Figure_2.jpeg)

![](_page_23_Figure_3.jpeg)

![](_page_23_Figure_4.jpeg)

![](_page_23_Picture_5.jpeg)

#### Mean Flow Isopycnal Depth (1027 kg/m<sup>3</sup>)

![](_page_24_Figure_1.jpeg)

![](_page_24_Figure_2.jpeg)

![](_page_24_Figure_3.jpeg)

![](_page_24_Picture_4.jpeg)

#### Mean Flow Isopycnal Depth (1027.5 kg/m<sup>3</sup>)

![](_page_25_Figure_1.jpeg)

![](_page_25_Picture_2.jpeg)

#### Energy Budgets

![](_page_26_Figure_1.jpeg)