

# CLIMATE MODELING ALLIANCE

Clouds, Climate, And Data-Informed Earth System Modeling

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### The Climate Modeling Alliance (CliMA)...

...is a coalition of scientists, engineers, and applied mathematicians from **Caltech**, **MIT**, the **Naval Postgraduate School**, and the **Jet Propulsion Laboratory.** We are building the first Earth system model that automatically learns from diverse data sources to produce accurate climate predictions with quantified uncertainties.



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**ERIC AND WENDY SCHMIDT** 

SCHMIDT FUTURES



#### CHARLES TRIMBLE

#### RONALD AND MAXINE LINDE CLIMATE CHALLENGE





#### **Limitations of Current Models**





Temperature change (°C) from 1850s through 2010s

Climate predictions are uncertain: E.g., the CO<sub>2</sub> concentration at which 2°C warming threshold is crossed varies widely across models



Schneider et al., Nature Climate Change 2017

#### Low clouds dominate uncertainty in projections





http://eoimages.gsfc.nasa.gov

#### Stratocumulus: colder

Cumulus: warmer

We don't know if we will get more low clouds (damped global warming), or fewer low clouds (amplified warming)

### More accurate climate projections with quantified uncertainties would enable...

- Data-driven decisions about infrastructure planning, e.g.,
  - How high a sea wall should New York City build to protect itself against storm surges in 2050?
  - What water management infrastructure is needed to ensure food and water security in sub-Saharan Africa?
- Rational resource allocation for climate change adaptation: costs estimated to reach >\$200B annually by 2050 (UNEP 2016)

Cumulative socioeconomic value of more accurate predictions estimated to lie in the trillions of USD (Hope 2015)

### Small-scale processes (e.g., clouds) are the primary sources of uncertainty in climate projections





Global model: ~10-50 km resolution

Cloud scales: ~10-100 m

Subgrid-scale processes (e.g., clouds and turbulence) are represented semi-empirically

The models' inability to predict low clouds is also manifest in failure to simulate present climate: E.g., no model simulates stratocumulus well



### A new approach: climate models that learn from diverse data sources

We are building an Earth system model (ESM) that learns automatically from two data sources

1. **Global observations**: Our ESM will learn from spacebased measurements of temperature, humidity, clouds, ocean surface currents, and sea ice cover

2. Local high-resolution simulations: Our ESM will learn from targeted high-resolution simulations of computable processes such as ocean turbulence, clouds, and convection

## A wealth of Earth observations is available, whose potential to improve models has not been tapped



# We can also simulate some processes (e.g., clouds) faithfully, albeit only in limited areas



Large-eddy simulation of tropical cumulus

Simulation with PyCLES (Pressel et al. 2015)

# Such limited area models can be nested in a global model and can, in turn, inform the global model



Thousands or tens of thousands of high-resolution simulations can be embedded in a global model, and the global model can learn from them

#### Our ESM will learn from observations and targeted highresolution simulations by optimizing over climate statistics

We are using statistics accumulated in time (e.g., over seasons) to

- 1. *Minimize model biases,* especially biases that are known to correlate with the climate response of models. That is, we will minimize mismatches between time averages of ESM-simulated quantities and data, directly targeting quantities relevant for climate predictions.
- 2. *Minimize model-data mismatches in higher-order Earth system statistics,* e.g., covariances such as cloud-cover/surface temperature covariances, which are known to correlate with the climate response of models. Higher-order statistics relevant for predictions (e.g., precipitation extremes) are also included in objective function.

### Example of large biases in climate models: temperature and sea ice in Arctic



- Arctic temperatures and sea ice cover in current climate models have large biases
- This has enormous implications, e.g., for cryosphere, ecosystems, and hydrological impacts (CA drought)
- Reducing biases represents opportunity to improve models, including predictive capabilities

# Keys to predictive success and computational feasibility

- We need out-of-sample predictive capabilities (predict a climate we have not seen)
  - Use known equations of motion to the extent possible to minimize number of adjustable parameters and avoid overfitting
- Running ESMs is computationally extremely expensive, hence computational efficiency is essential
  - For optimization, use ensemble methods (Kalman inversion and variants) that easily parallelize
  - For uncertainty quantification, use ML tools (e.g., Gaussian process emulation) to create surrogate models

### One example of new SGS scheme: turbulence/ convection scheme for all forms of SGS turbulence

Decomposes domain into environment (i=0) and updrafts (i=1, ..., N):

• Continuity: 
$$\frac{\partial(\rho a_i)}{\partial t} + \frac{\partial(\rho a_i \overline{w}_i)}{\partial z} + \nabla_h \cdot (\rho a_i \langle \mathbf{u}_h \rangle) = \rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} - \delta_i\right)$$

Mass entrainment/detrainment

• Scalar mean:

$$\frac{\partial(\rho a_i \overline{\phi}_i)}{\partial t} + \frac{\partial(\rho a_i \overline{w}_i \overline{\phi}_i)}{\partial z} + \nabla_h \cdot \left(\rho a_i \langle \mathbf{u}_h \rangle \overline{\phi}_i\right) = \underbrace{-\frac{\partial(\rho a_i \overline{w}_i \phi_i')}{\partial z}}_{\text{Turbulent transport}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Fatainment of straines and }} + \underbrace{\rho a_i \overline{\phi}_j - \delta_i \overline{\phi}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_j - \delta_i \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \left(\sum_j \epsilon_{ij} \overline{\phi}_i\right)}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \overline{\phi}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \overline{\phi}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i \overline{\phi}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i \overline{w}_i}_{\text{Sources/sinks}} + \underbrace{\rho a_i$$

Entrainment/detrainment

Scalar covariance

$$\frac{\partial(\rho a_i \overline{\phi'_i \psi'_i})}{\partial t} + \frac{\partial(\rho a_i \overline{w}_i \overline{\phi'_i \psi'_i})}{\partial z} + \nabla_h \cdot \left(\rho a_i \langle \mathbf{u}_h \rangle \overline{\phi'_i \psi'_i}\right) = \underbrace{-\rho a_i \overline{w'_i \psi'_i}}_{\partial z} \frac{\partial \overline{\phi}_i}{\partial z} - \rho a_i \overline{w'_i \phi'_i} \frac{\partial \overline{\psi}_i}{\partial z}$$

Generation/destruction by cross-gradient flux

$$+ \underbrace{\rho a_i \overline{w}_i \left[ \sum_j \epsilon_{ij} (\overline{\phi'_j \psi'_j} + (\overline{\phi}_j - \overline{\phi}_i) (\overline{\psi}_j - \overline{\psi}_i)) - \delta_i \overline{\phi'_i \psi'_i} \right]}_{\text{Turbulent transport}} - \underbrace{\frac{\partial (\rho a_i \overline{w'_i \phi'_i \psi'_i})}{\partial z}}_{\text{Sources/sinks}} + \underbrace{\rho a_i (\overline{S'_{\phi,i} \psi'_i} + \overline{S'_{\psi,i} \phi'_i})}_{\text{Sources/sinks}}.$$

Covariance entrainment/detrainment

### We are currently building a modeling platform with a fresh architecture that integrates all of these elements



**Targeted High-Resolution Simulations** 

### Approximate Bayesian calibration and uncertainty quantification for climate models: Calibrate, emulate, sample



Andrew Stuart



Emmet Cleary



Alfredo Garbuno

### Learning about parameters in convection scheme of an idealized climate model as proof-of-concept

- GCM is an idealized aquaplanet model
- It has a convection scheme that relaxes temperature *T* and specific humidities *q* to reference profiles

$$\partial_t T + v \cdot \nabla T + \dots = -\frac{T - T_{\text{ref}}}{\tau}$$
$$\partial_t q + v \cdot \nabla q + \dots = -\frac{q - RH_{\text{ref}}q^*(T_{\text{ref}})}{\tau}$$

- Two closure parameters: timescale  $\tau$  and reference relative humidity RH<sub>ref</sub>
- Objective function contains 96 terms (tropospheric relative humidity, precipitation, and precipitation extremes in 32 latitude bands)

### Three steps: (1) Calibration by ensemble Kalman inversion (converges quickly, but ensemble collapses)



Optimization of parameters in convection scheme in an idealized GCM: ensemble of size 100 converges in ~5 iterations

Objective function has **relative humidity**, **mean precipitation**, and **precipitation extremes** 

# (2) Model emulation to recover the posterior distribution lost in optimization

• Train a Gaussian process model during the ensemble optimization, at minimal marginal computational cost



### (3) Sample from emulated posterior for uncertainty quantification



MCMC (500,000 iterations) on GP trained on ensemble gives good estimate of posterior PDF of parameters

# We will use the same approach for calibration *all* components of the ESM *jointly*



Much interesting work (SGS models, UQ, effective filtering, optimal targeting of high-res simulations...) remains to be done!

Clouds

# Within 5 years, we will build an ESM platform that...

- Integrates data and nested high-resolution simulations from the outset in a learning environment
- Implements data assimilation and machine learning algorithms that are efficient enough for ESMs
- Has quantified uncertainties
- Will form basis for an ecosystem of applications (infrastructure planning, flood risk assessment, disaster planning etc.)

To ensure a sustainable educational pipeline in quantitative Earth science, we are establishing cross-links between graduate programs in computational and applied mathematics and in environmental science and engineering