

Data-driven parameterization of mesoscale eddies using the Eliassen-Palm flux

CLIVAR-OMDP Workshop, September 2024

Kelsey Everard¹, Pavel Perezhogin¹, Dhruv Balwada², Alistair Adcroft^{3,4}, Laure Zanna¹

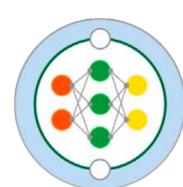
¹ Courant Institute of Mathematical Sciences, New York University

² Lamont-Doherty Earth Observatory, Columbia University

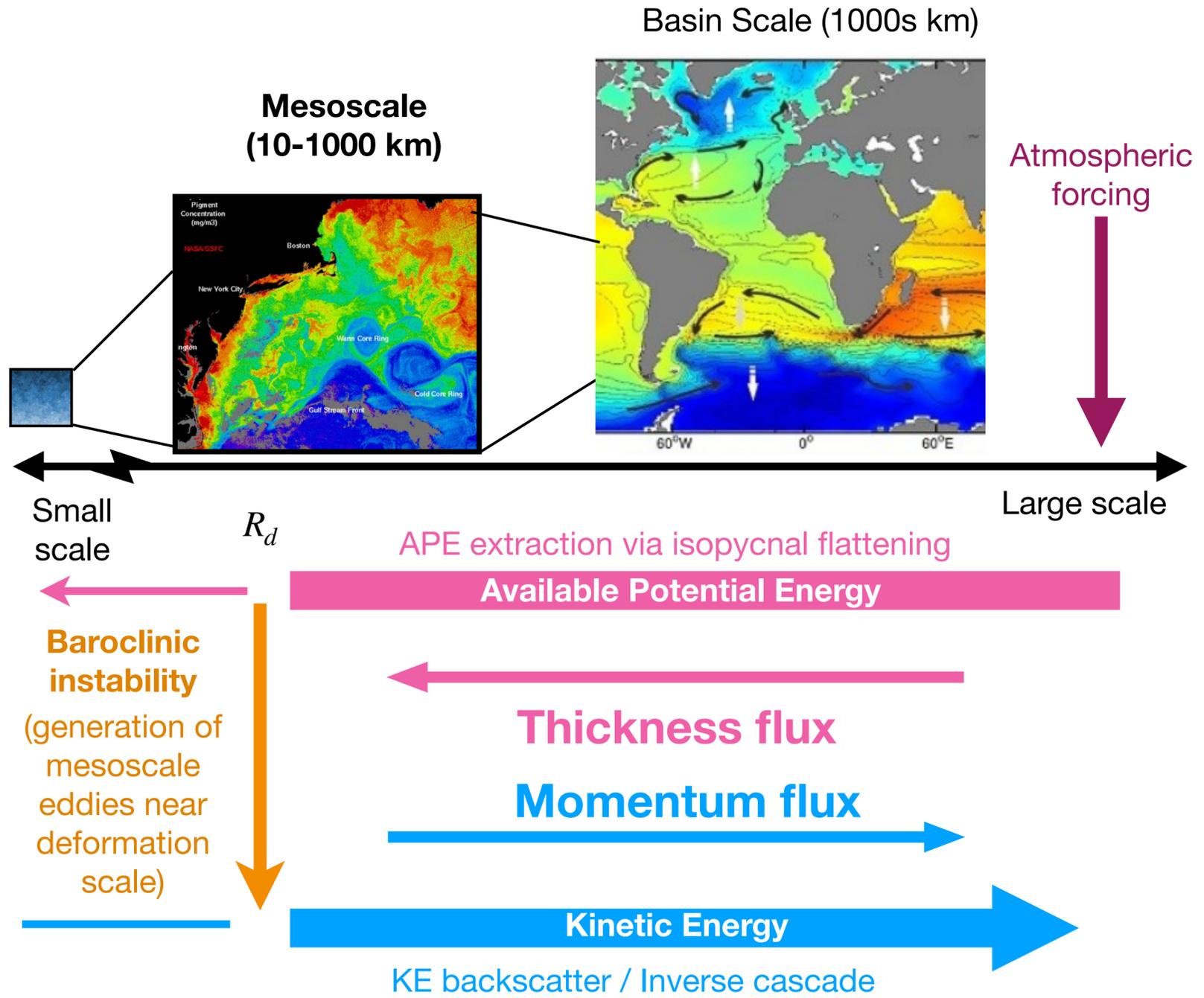
³ Geophysical Fluid Dynamics Laboratory, National Oceanic and Atmospheric Administration

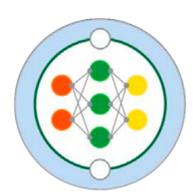
⁴ Atmospheric and Oceanic Sciences Program, Princeton University



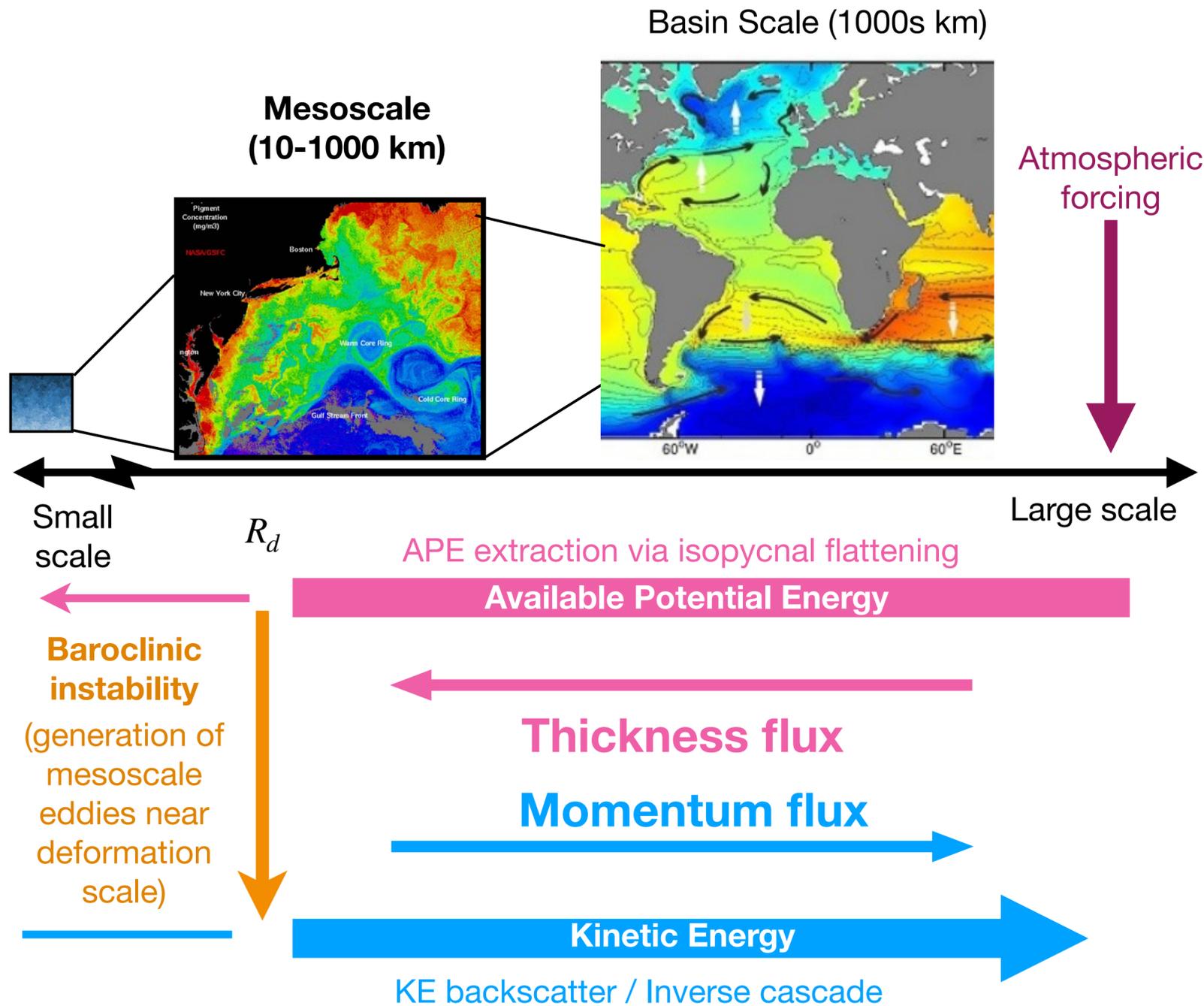


Mesoscale Eddy Energy Cycle





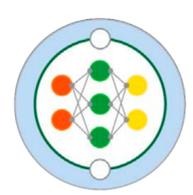
Energy cycle: A goal



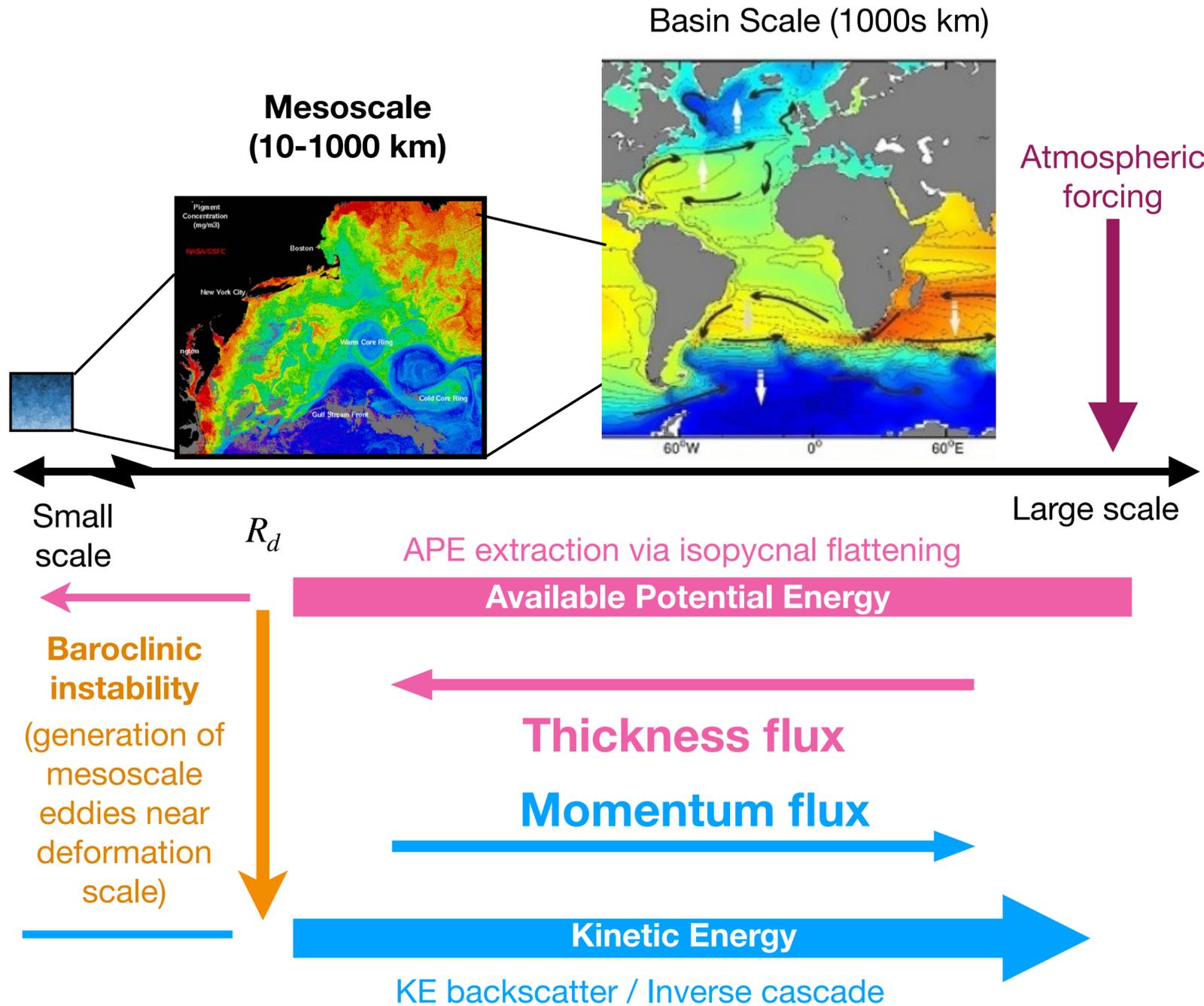
Down-scale energy transfer via APE extraction and up-scale energy transfer via KE backscatter are often parameterised separately

e.g., Kraichnan 1976; Frederiksen 1997; Berner 2009; Jansen 2014
 e.g., Gent McWilliams 1990; Griffies 1998

But they're two essential aspects of one process



Energy cycle: A goal

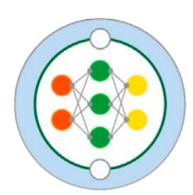


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But they're two essential aspects of one process

Parameterisation of Ocean mesoscale eddies whereby **momentum** and **thickness** fluxes are considered *together*



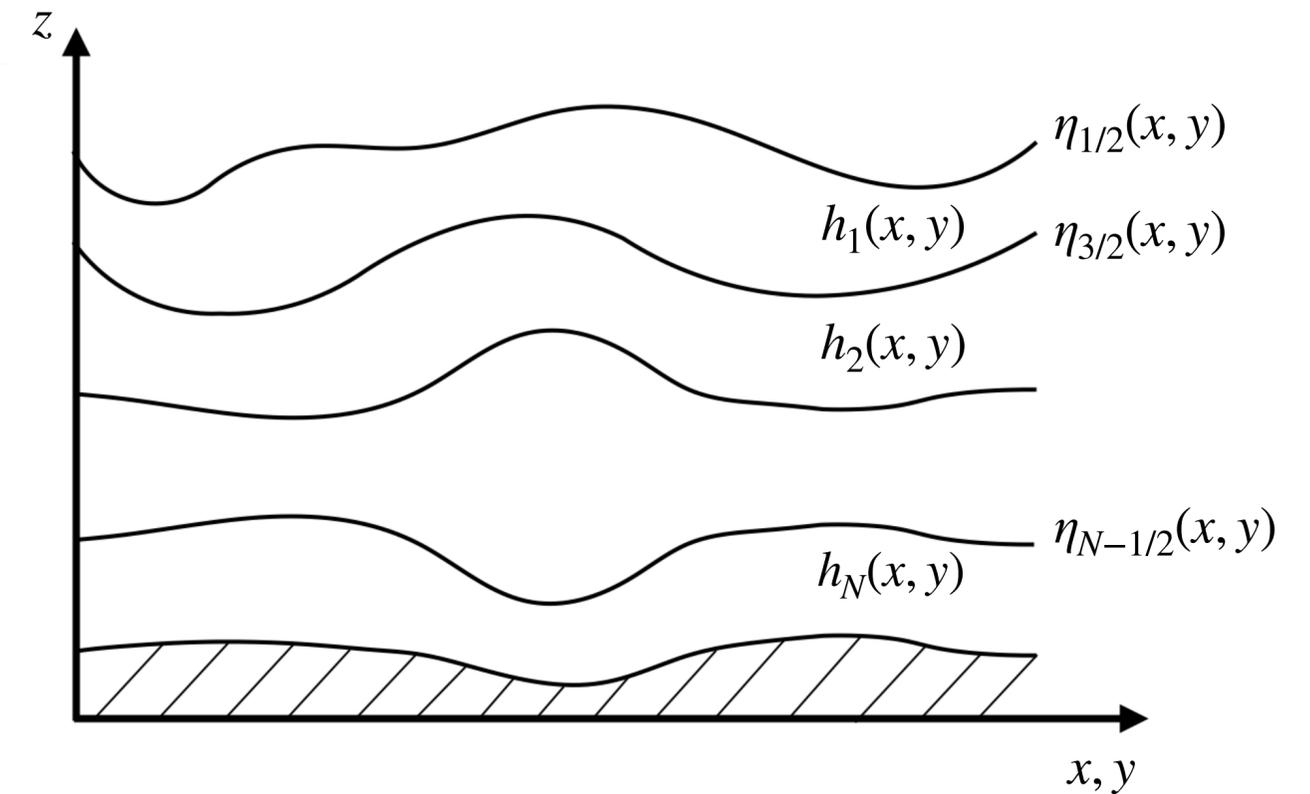
Energy + Momentum + Thickness = Eliassen-Palm Flux

To capture the full eddy energy cycle, we target the Eliassen-Palm Flux

Thickness-weighted average framework: $\hat{u}_n = \frac{\overline{h_n u_n}}{\bar{h}_n}$ Thickness weighted average

$$\frac{\partial \hat{u}_n}{\partial t} + \hat{u}_n \frac{\partial \hat{u}_n}{\partial x} + \hat{v}_n \frac{\partial \hat{u}_n}{\partial y} - f \hat{v}_n + \frac{\partial \bar{p}_n}{\partial x} - \widehat{F}_n^{(u)} = -\nabla_3 \cdot \widehat{E}_n^{(u)}$$

$$\frac{\partial \hat{v}_n}{\partial t} + \hat{u}_n \frac{\partial \hat{v}_n}{\partial x} + \hat{v}_n \frac{\partial \hat{v}_n}{\partial y} + f \hat{u}_n + \frac{\partial \bar{p}_n}{\partial y} - \widehat{F}_n^{(v)} = -\nabla_3 \cdot \widehat{E}_n^{(v)}$$

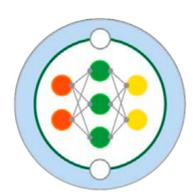


$$\widehat{\mathbf{E}}_n = \begin{pmatrix} \widehat{E}_n^{(u)} \\ \widehat{E}_n^{(v)} \end{pmatrix} = \begin{pmatrix} \left(\overline{u_n'^2} + \frac{1}{2\bar{h}_n} g_{n-1/2}^r \overline{\eta_{n-1/2}'^2} \right) & \left(\overline{u_n' v_n'} \right) \\ \left(\overline{u_n' v_n'} \right) & \left(\overline{v_n'^2} + \frac{1}{2\bar{h}_n} g_{n-1/2}^r \overline{\eta_{n-1/2}'^2} \right) \\ \left(\overline{\eta_{n-1/2}' \frac{\partial}{\partial x} p_{n-1}'} \right) & \left(\overline{\eta_{n-1/2}' \frac{\partial}{\partial y} p_{n-1}'} \right) \end{pmatrix}$$

Eliassen-Palm Flux

Zonal Meridional

Thickness fluxes projected onto momentum equations!



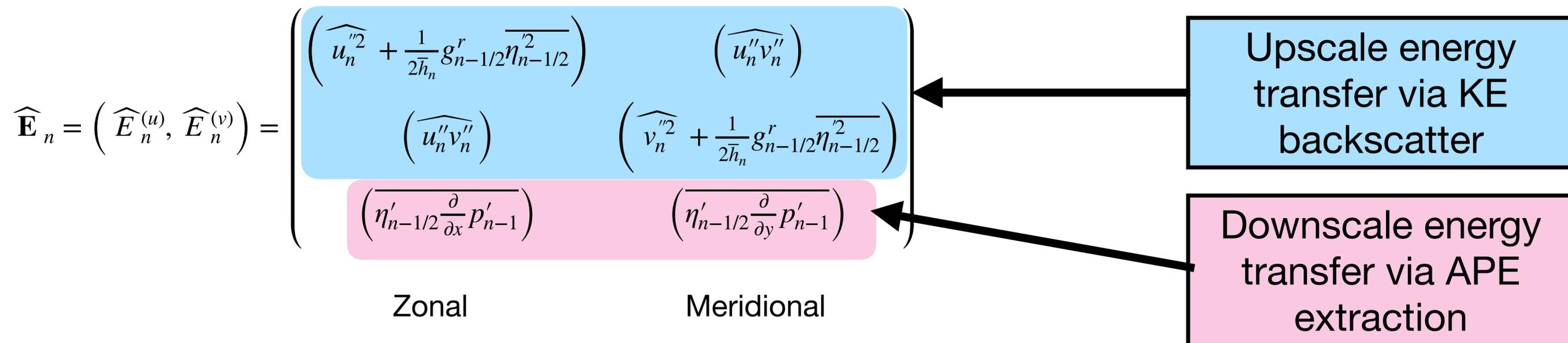
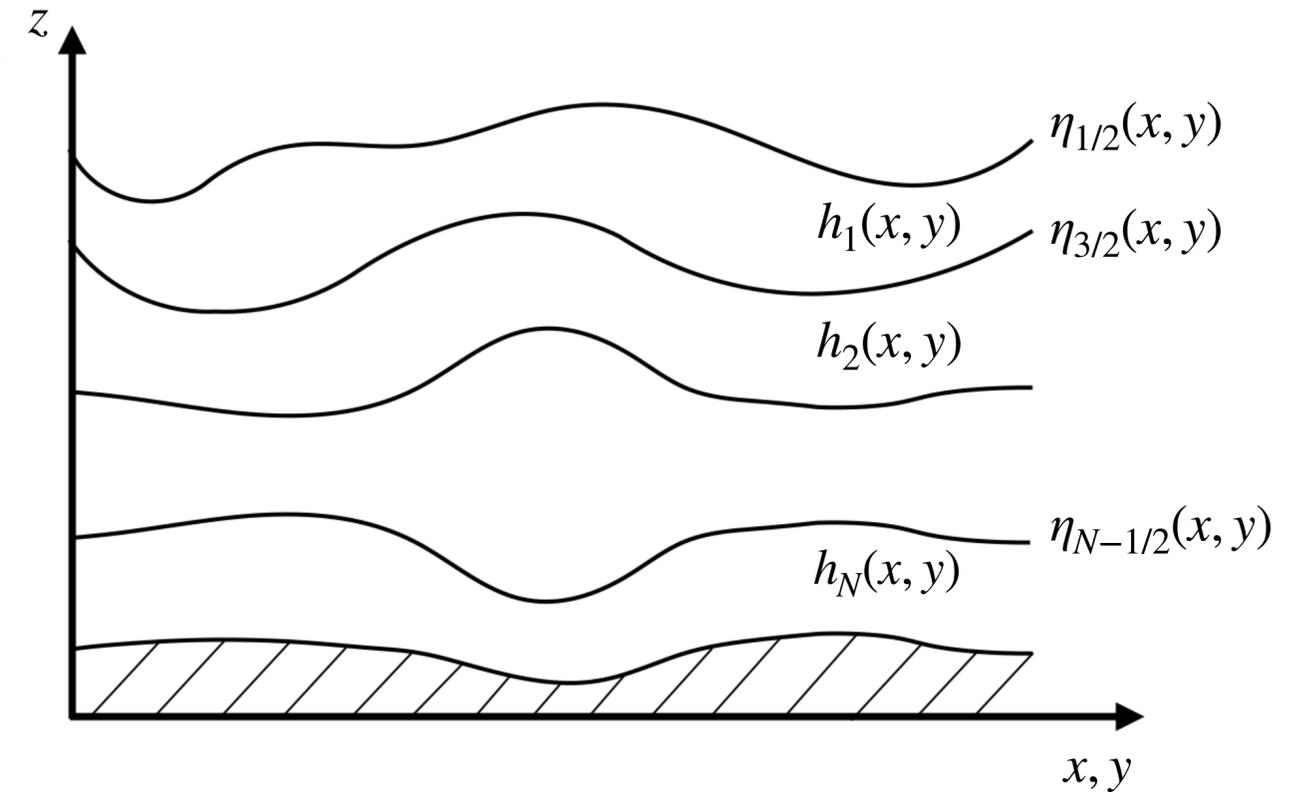
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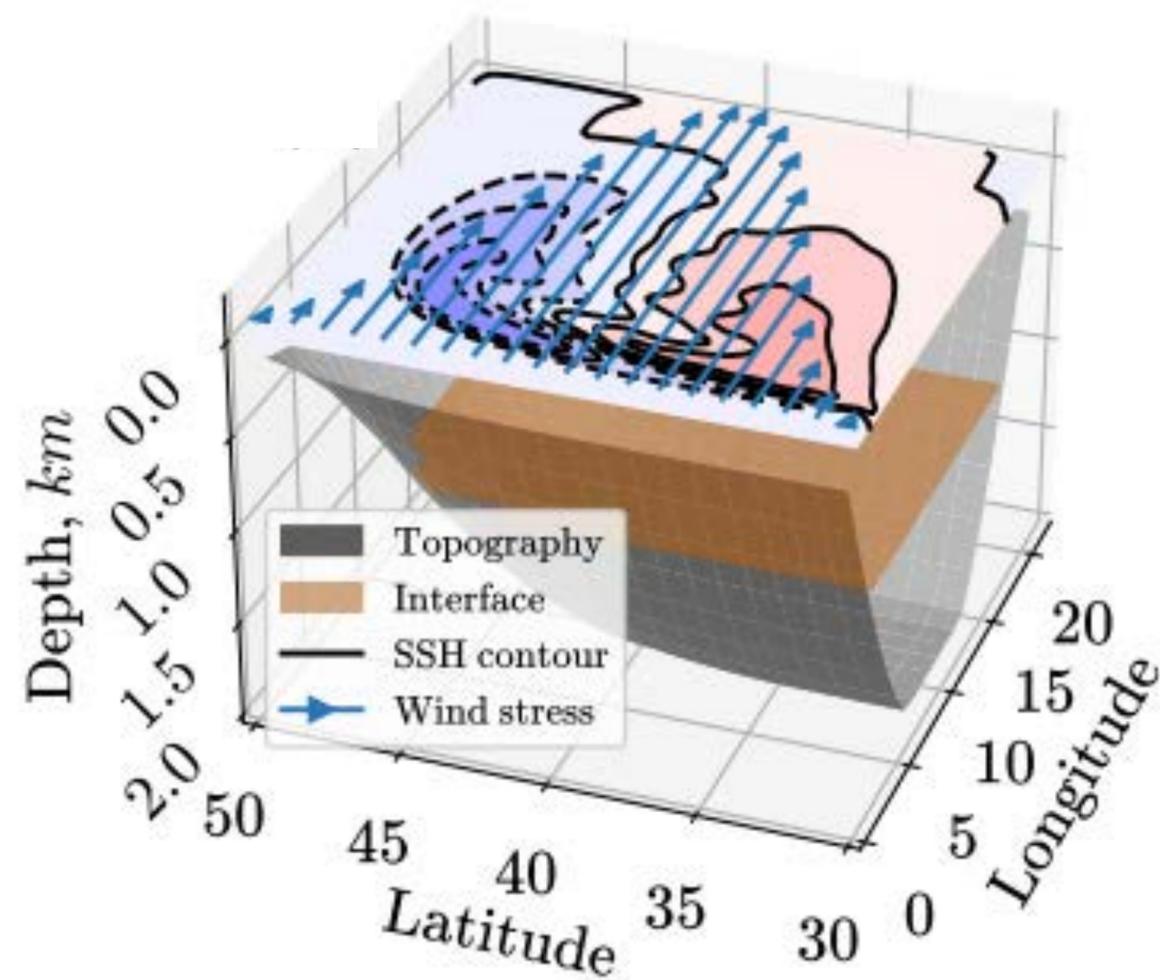
Thickness-weighted average framework: $\hat{u}_n = \frac{\overline{h_n u_n}}{\bar{h}_n}$ Thickness weighted average

$$\frac{\partial \hat{u}_n}{\partial t} + \hat{u}_n \frac{\partial \hat{u}_n}{\partial x} + \hat{v}_n \frac{\partial \hat{u}_n}{\partial y} - f \hat{v}_n + \frac{\partial \bar{p}_n}{\partial x} - \widehat{F}_n^{(u)} = -\nabla_3 \cdot \widehat{E}_n^{(u)}$$

$$\frac{\partial \hat{v}_n}{\partial t} + \hat{u}_n \frac{\partial \hat{v}_n}{\partial x} + \hat{v}_n \frac{\partial \hat{v}_n}{\partial y} + f \hat{u}_n + \frac{\partial \bar{p}_n}{\partial y} - \widehat{F}_n^{(v)} = -\nabla_3 \cdot \widehat{E}_n^{(v)}$$



MOM6 Double Gyre Configuration



Perezhogin et al (2024)

Commonly used configuration as stepping stone e.g.,

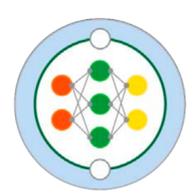
Dhruv's presentation;

Perezhogin et al (2024);

Zhang et al (2023)

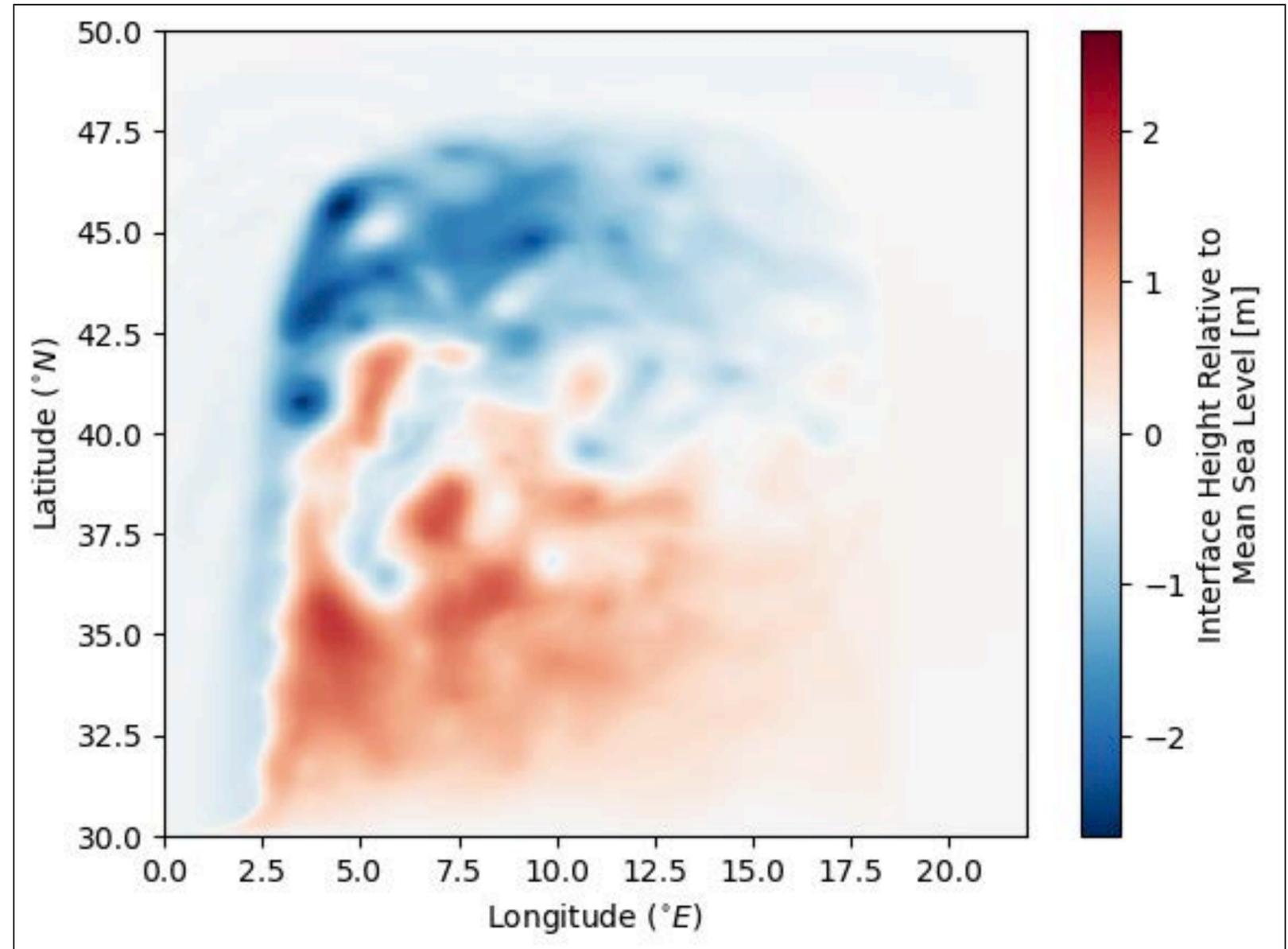
GFDL MOM6 ocean model in Double Gyre configuration

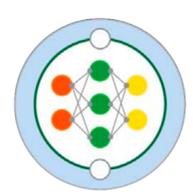
- Two layers
- Initialized from rest
- Driven by wind and equilibrated by bottom friction
- Biharmonic Smagorinsky model



Parameterisation Development: 1) High resolution data

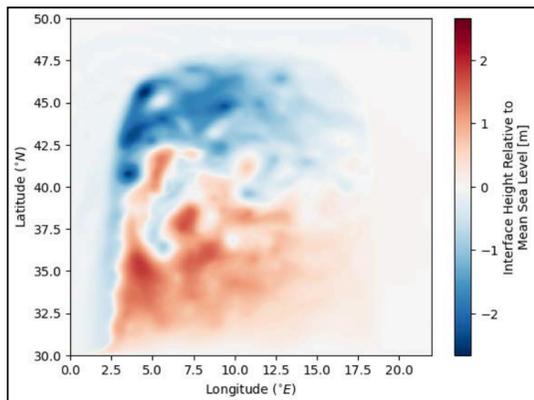
Double Gyre simulation data at
 $1/32^\circ$ resolution



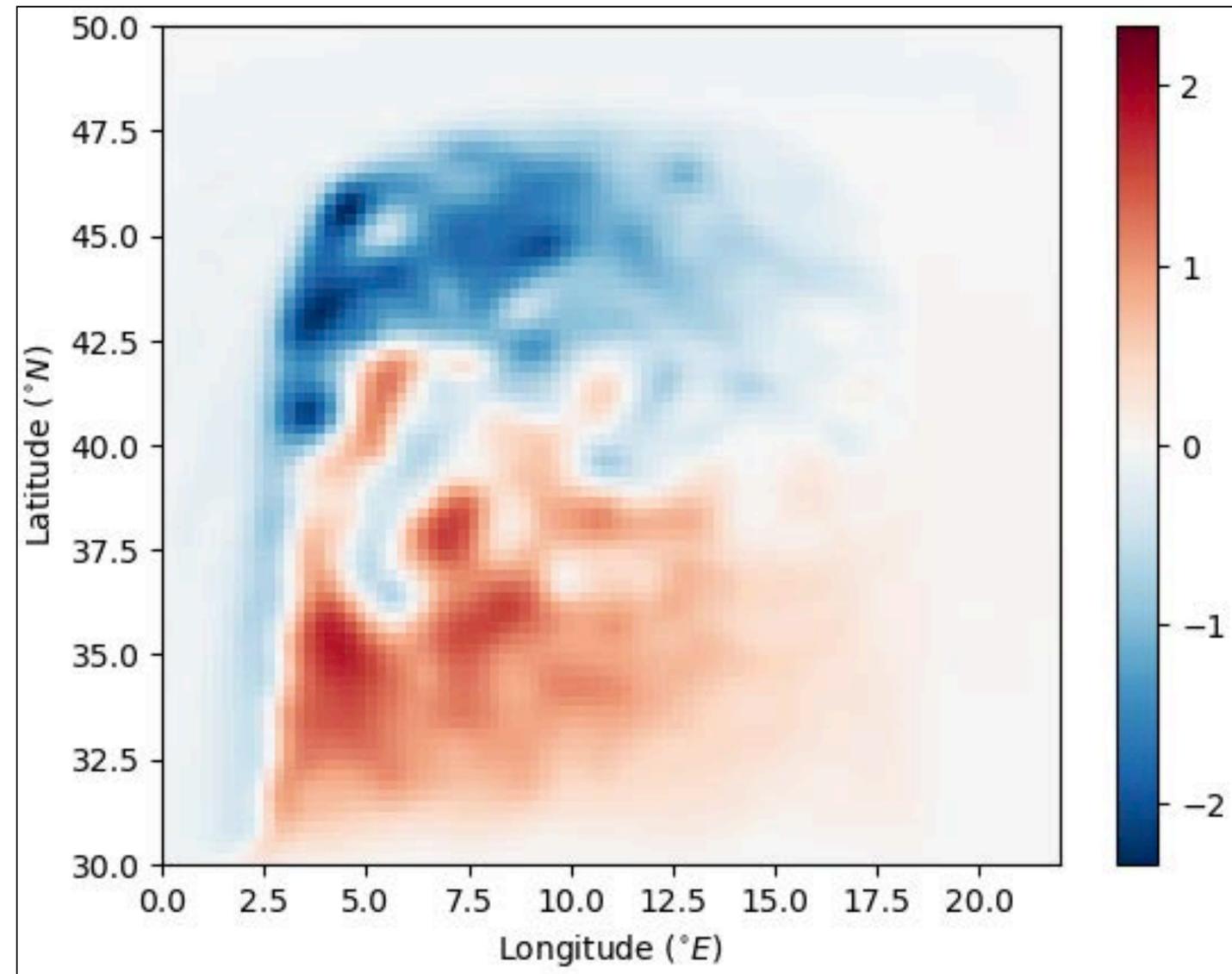


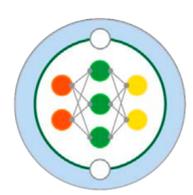
Parameterisation Development: 2) Filter and coarsen

Double Gyre
simulation data at
 $1/32^\circ$ resolution



Filter and coarsen to $1/4^\circ$



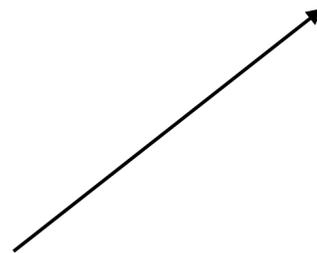


Parameterisation Development: 3) Coarse flow-field representations

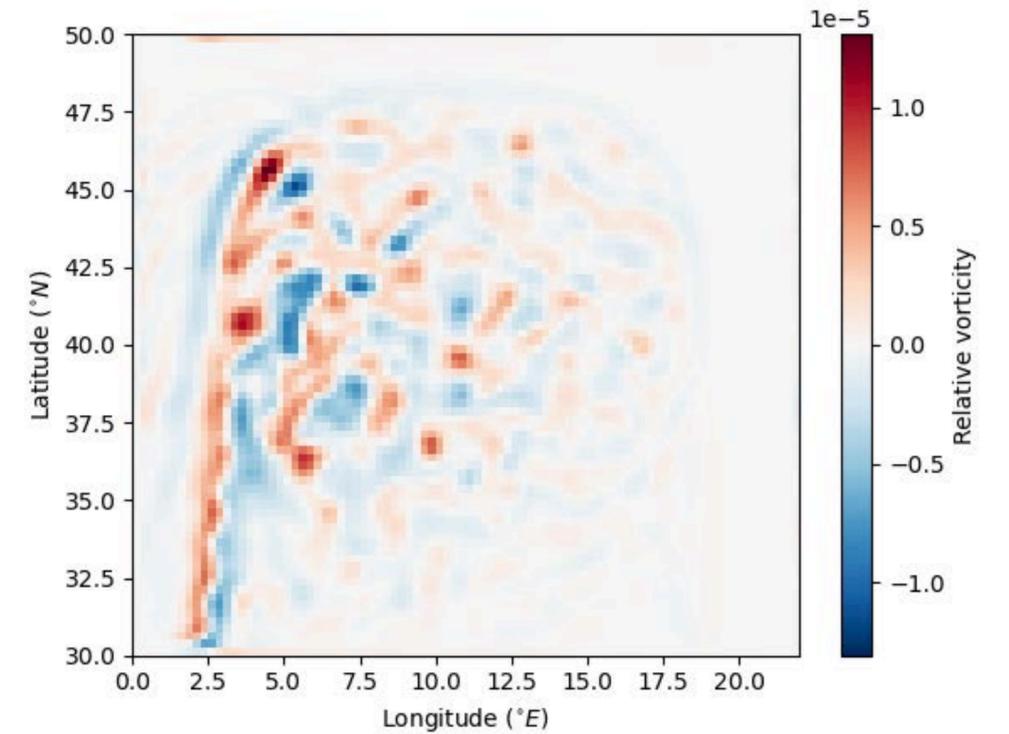
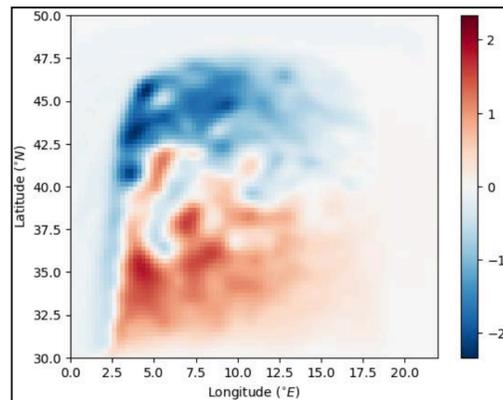
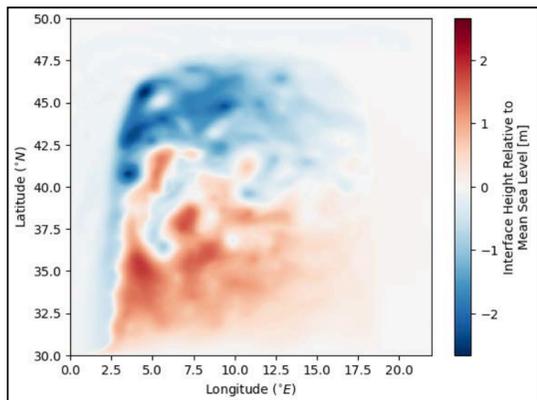
Double Gyre simulation data at $1/32^\circ$ resolution

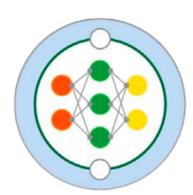


Filter and coarsen to $1/4^\circ$



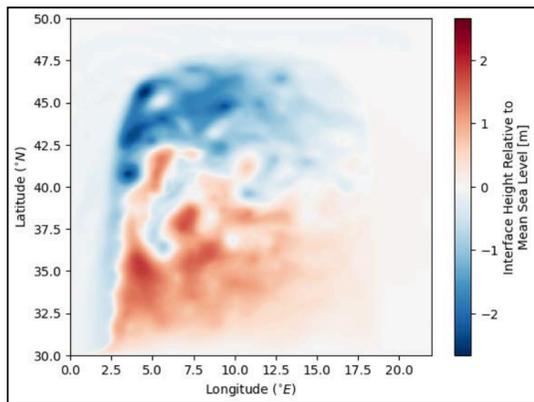
Calculate Spatial gradients of flow field variables



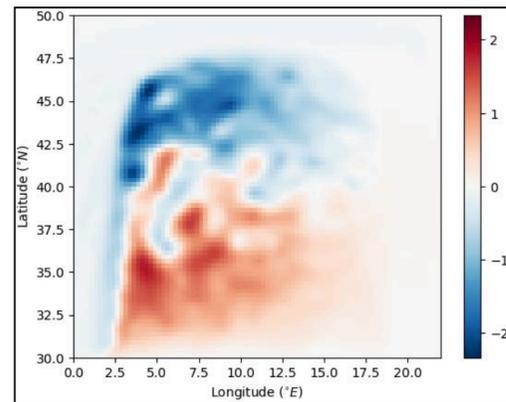


Parameterisation Development: 4) Diagnose Eliassen-Palm Fluxes

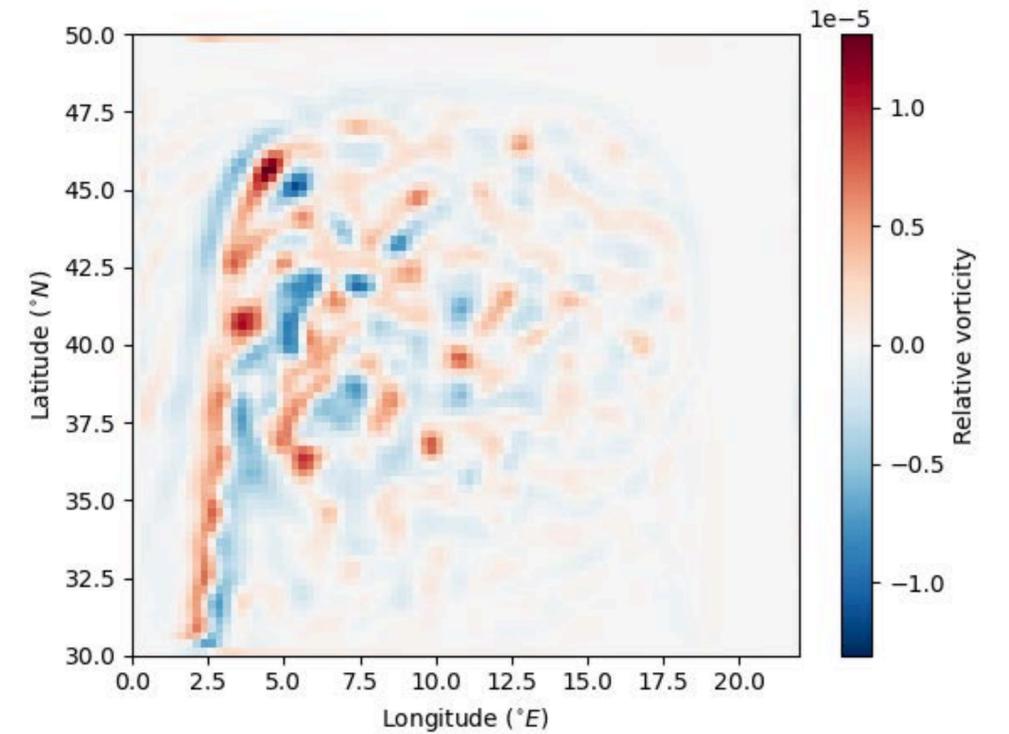
Double Gyre simulation data at $1/32^\circ$ resolution



Filter and coarsen to $1/4^\circ$

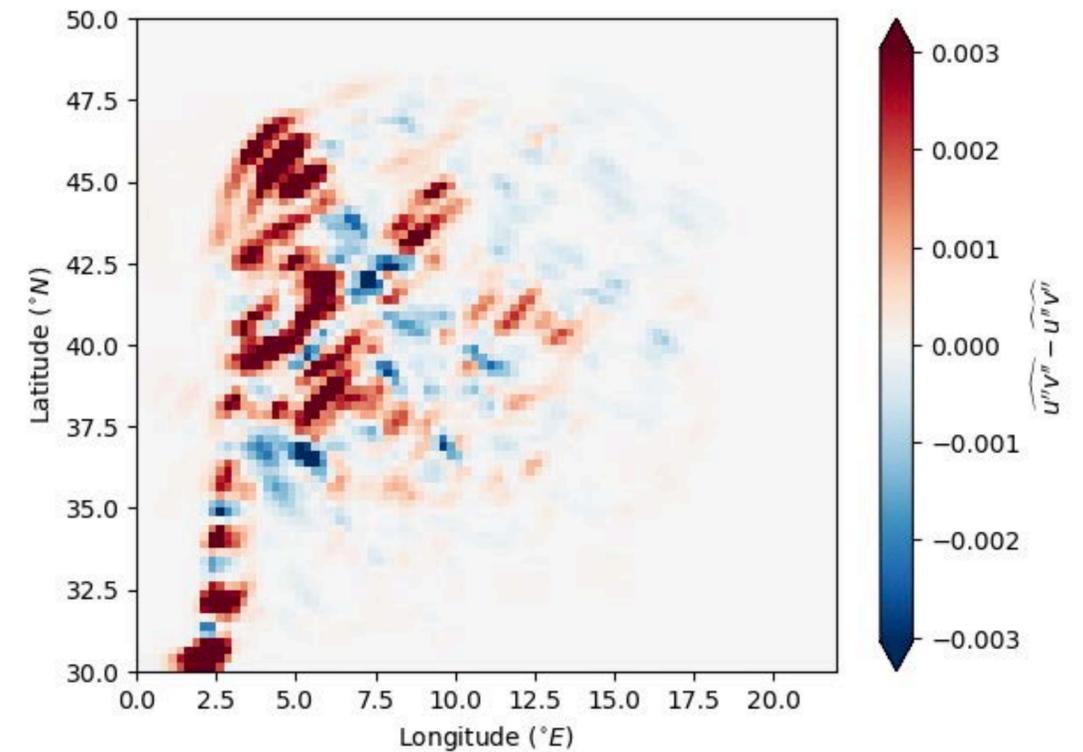


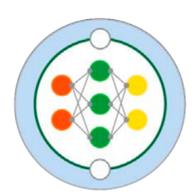
Calculate Spatial gradients of flow field variables



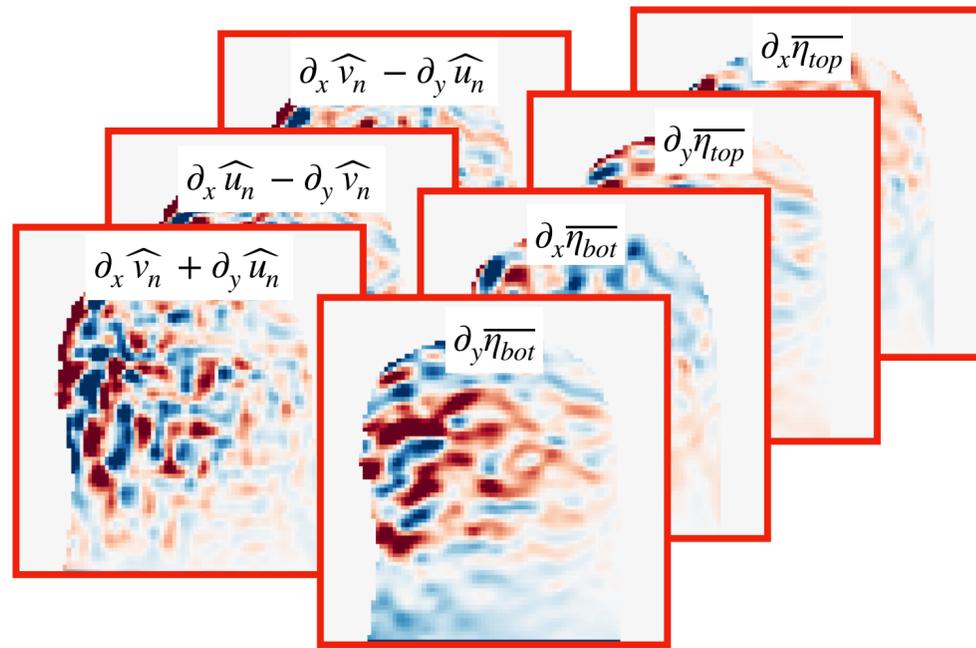
AND

Calculate Sub-filter EPF tensor components



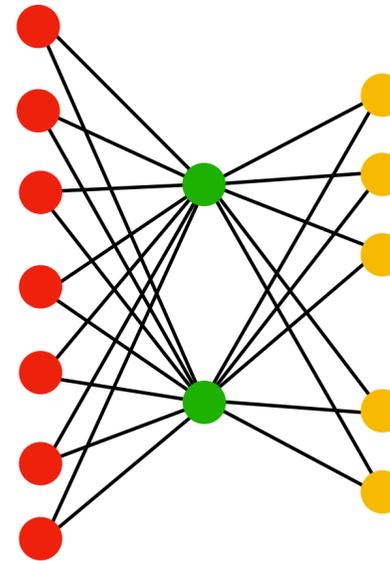


Parameterisation Development: 5) Artificial Neural Network

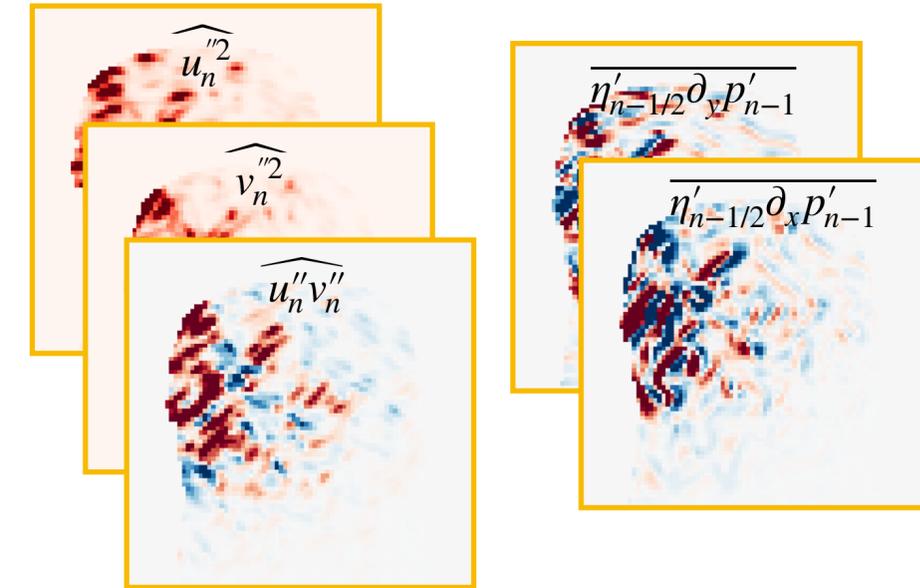


INPUTS:

- Coarse-grain derivatives of filtered flow variables



2 hidden layers
8 neurons each



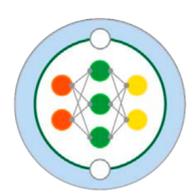
OUTPUTS:

- Reynolds' stresses and dual form stresses

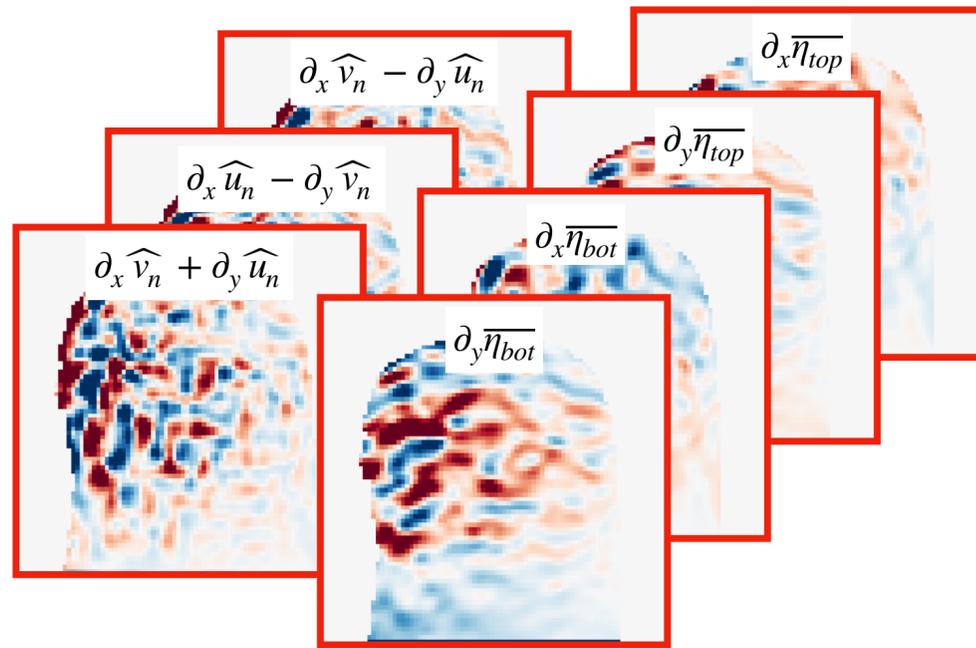
Trained on $\sim 4 \times 10^6$ samples (288 snapshots)

$\sim 5 \times 10^5$ samples for validation (36 snapshots)

$\sim 5 \times 10^5$ samples for testing (36 snapshots)

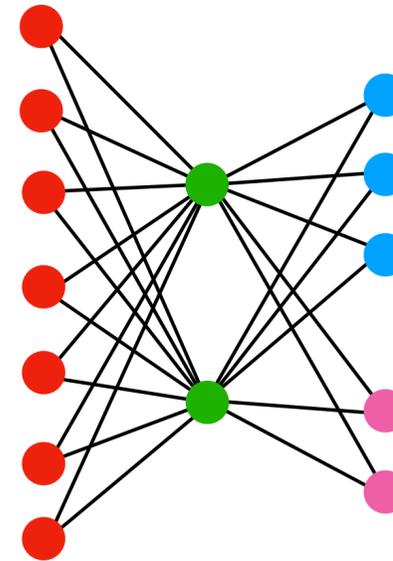


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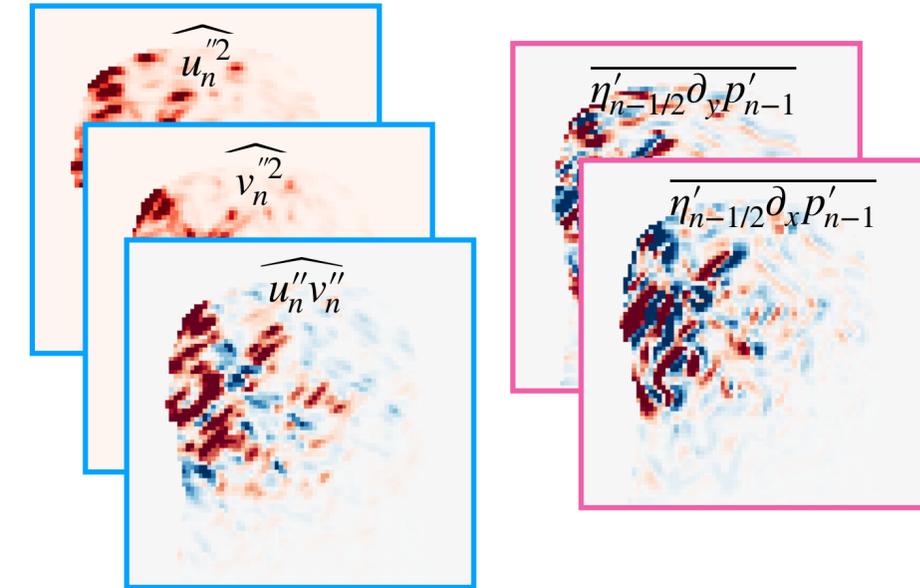


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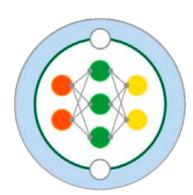


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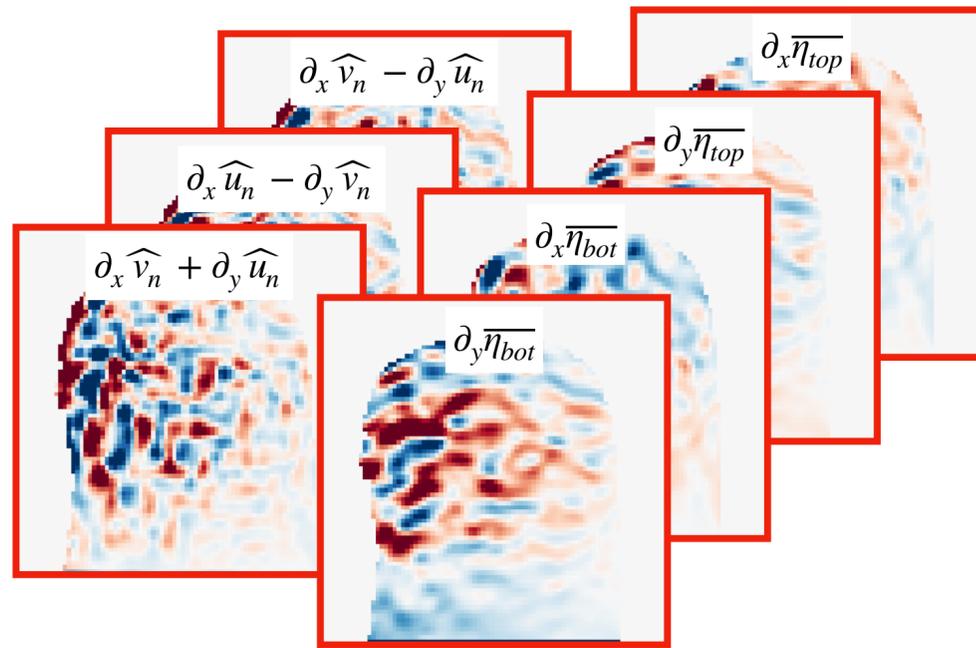


Upscale energy
transfer via KE
backscatter

$$\widehat{\mathbf{E}}_n = \left(\widehat{E}_n^{(u)}, \widehat{E}_n^{(v)} \right) = \begin{pmatrix} \left(\widehat{u_n''^2} + \frac{1}{2\overline{h}_n} \overline{g_{n-1/2}^r \eta_{n-1/2}^2} \right) & \left(\widehat{u_n'' v_n''} \right) \\ \left(\widehat{u_n'' v_n''} \right) & \left(\widehat{v_n''^2} + \frac{1}{2\overline{h}_n} \overline{g_{n-1/2}^r \eta_{n-1/2}^2} \right) \\ \left(\overline{\eta'_{n-1/2} \frac{\partial}{\partial x} p'_{n-1}} \right) & \left(\overline{\eta'_{n-1/2} \frac{\partial}{\partial y} p'_{n-1}} \right) \end{pmatrix}$$

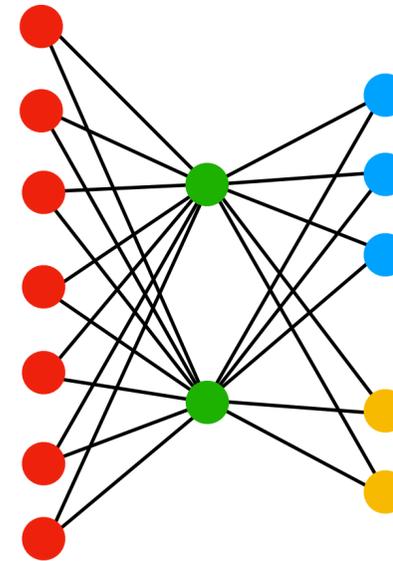


Parameterisation Development: 5) Artificial Neural Network

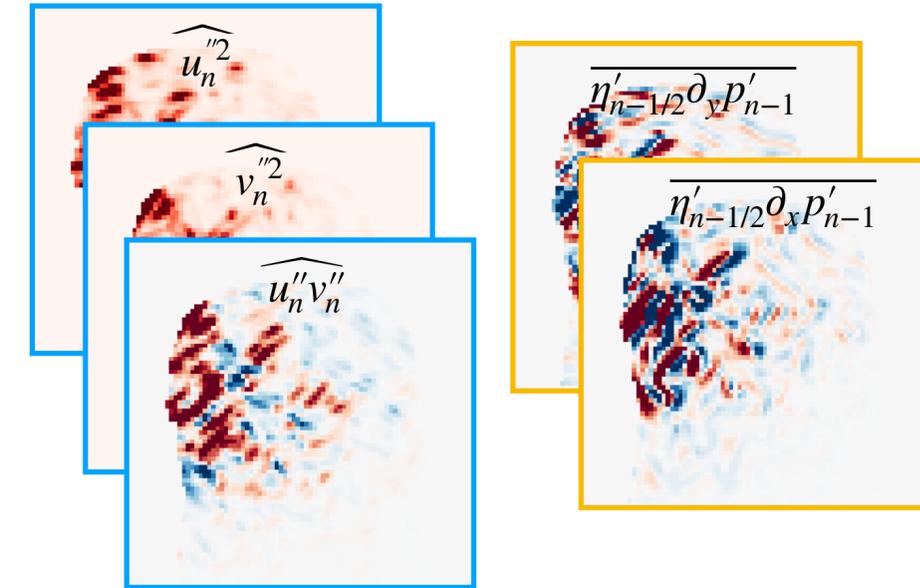


INPUTS:

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2 hidden layers
8 neurons each

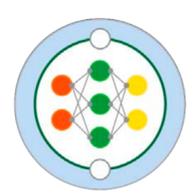


Upscale energy transfer via KE backscatter

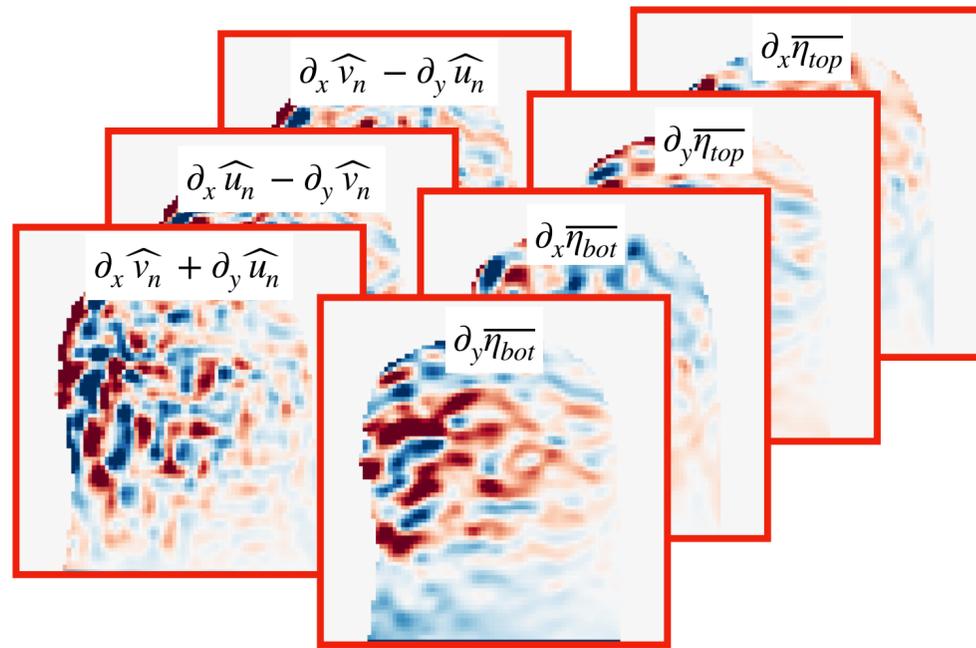
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Neglecting sub-filter potential energy

e.g., Marshall et al (2012)

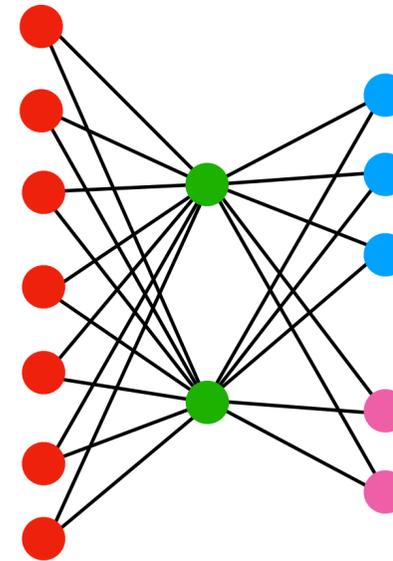


Parameterisation Development: 5) Artificial Neural Network

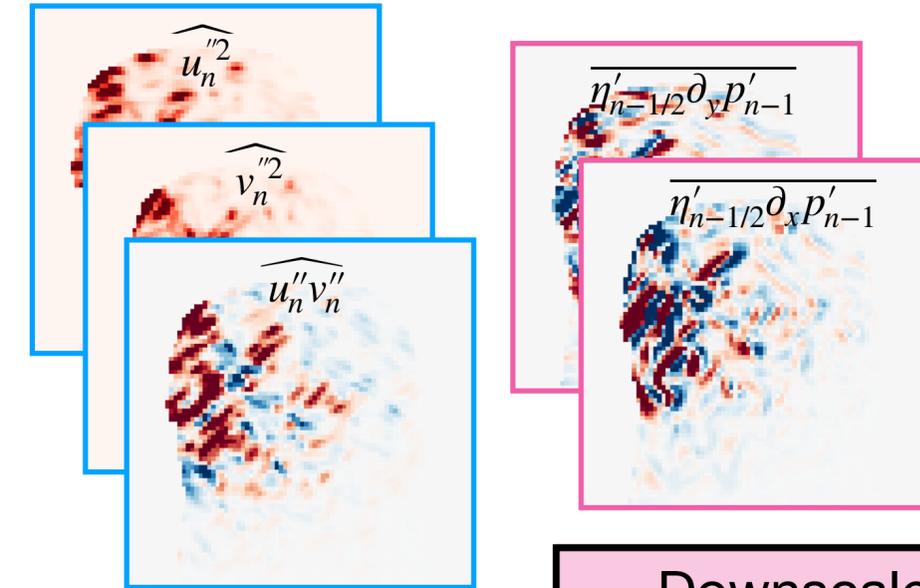


INPUTS:

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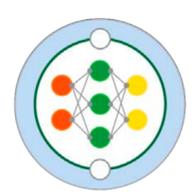
2 hidden layers
8 neurons each



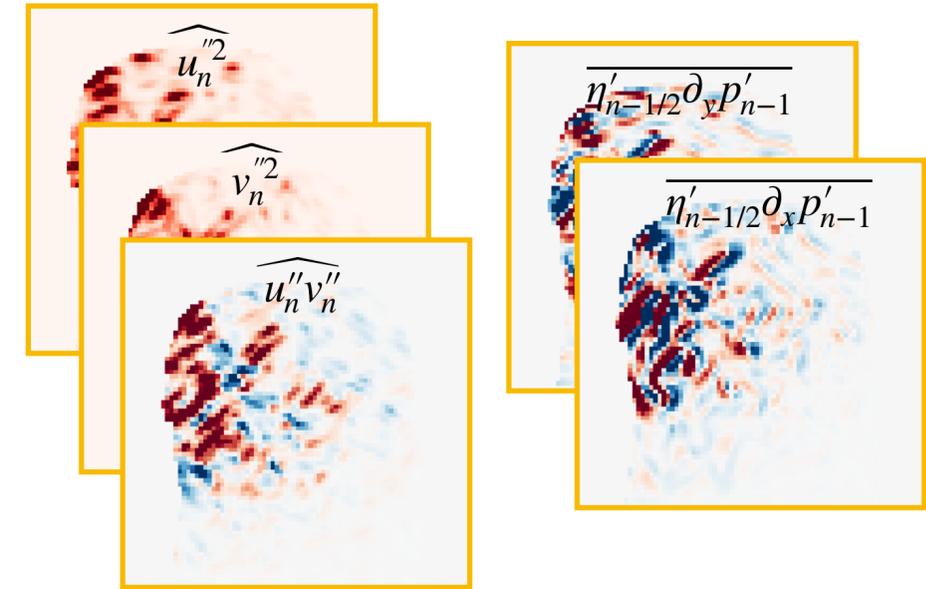
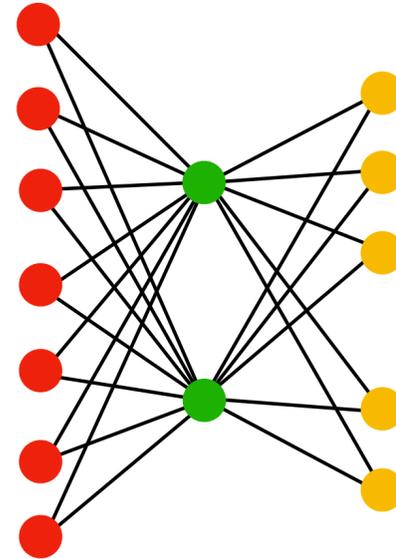
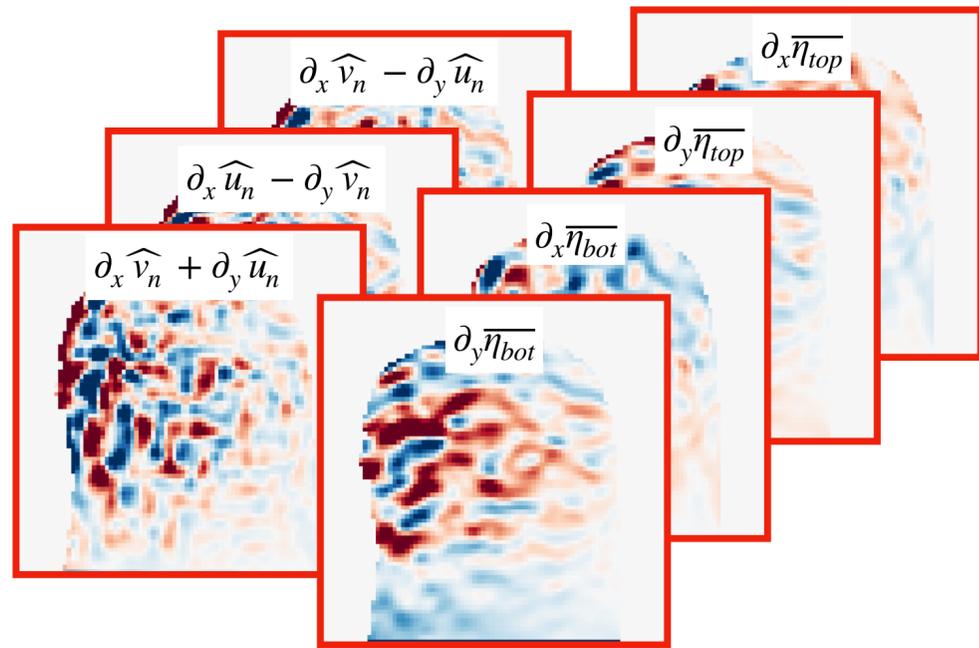
Upscale energy transfer via KE backscatter

Downscale energy transfer via APE extraction

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Parameterisation Development: 5) Artificial Neural Network



Momentum flux components

$$\Delta x^2 ||\nabla u||^2 \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{mom}$$

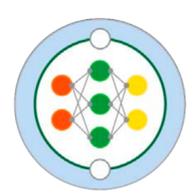
Normalized inputs

Thickness flux components

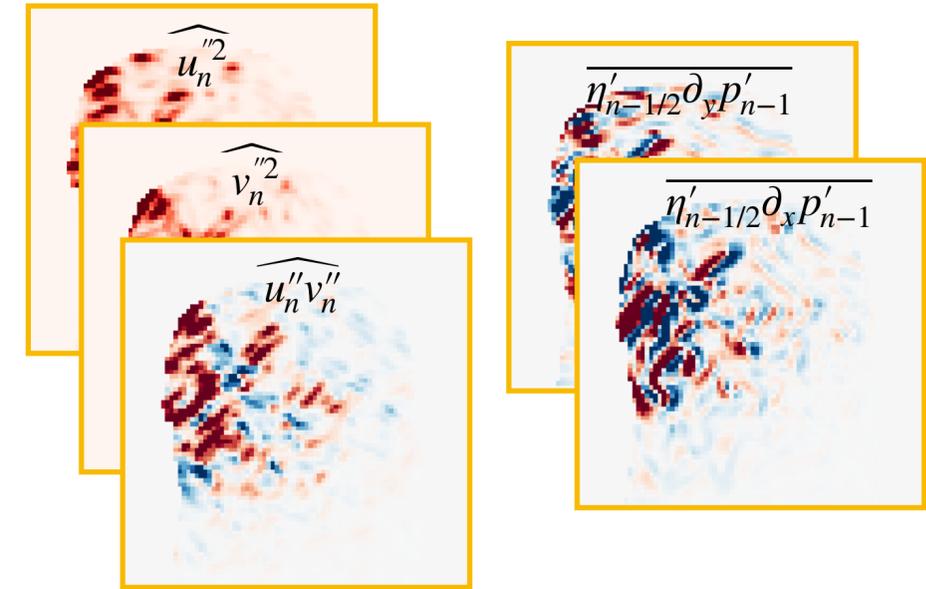
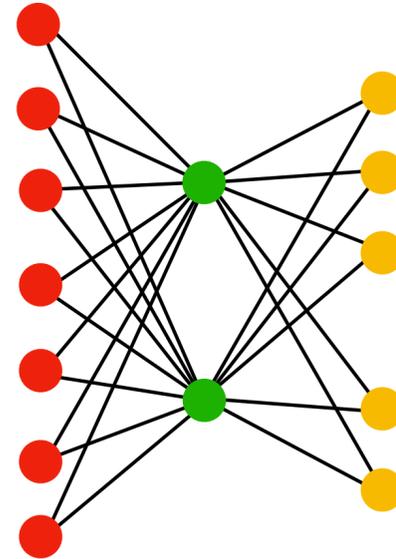
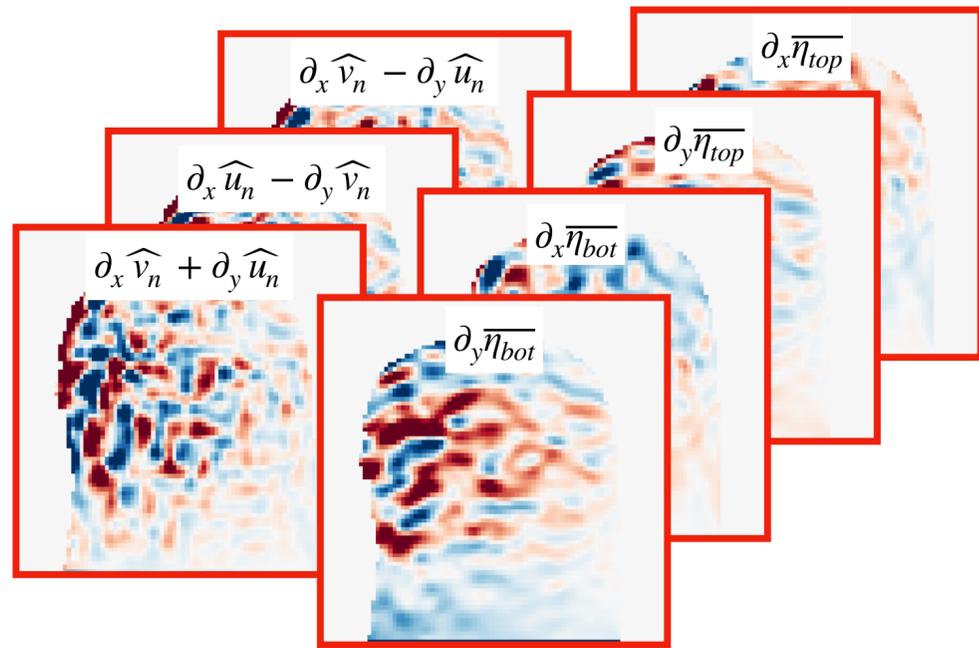
$$\Delta x^2 f ||\nabla u|| ||S|| \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{thick}$$

$$||\nabla u|| = \left(\left(\partial_x \widehat{v} - \partial_y \widehat{u} \right)^2 + \left(\partial_x \widehat{u} - \partial_y \widehat{v} \right)^2 + \left(\partial_x \widehat{v} + \partial_y \widehat{u} \right)^2 \right)^{1/2}$$

$$||S|| = \left(\left(\partial_x \overline{\eta}_{top} \right)^2 + \left(\partial_y \overline{\eta}_{top} \right)^2 + \left(\partial_x \overline{\eta}_{bot} \right)^2 + \left(\partial_y \overline{\eta}_{bot} \right)^2 \right)^{1/2}$$



Parameterisation Development: 5) Artificial Neural Network



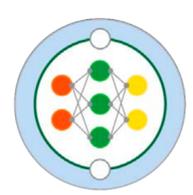
Momentum flux components

$$\Delta x^2 ||\nabla u||^2 \text{ANN} \left(\frac{||\nabla u||}{||S||}, \frac{S}{||S||} \right) \approx \widehat{E}_{mom}$$

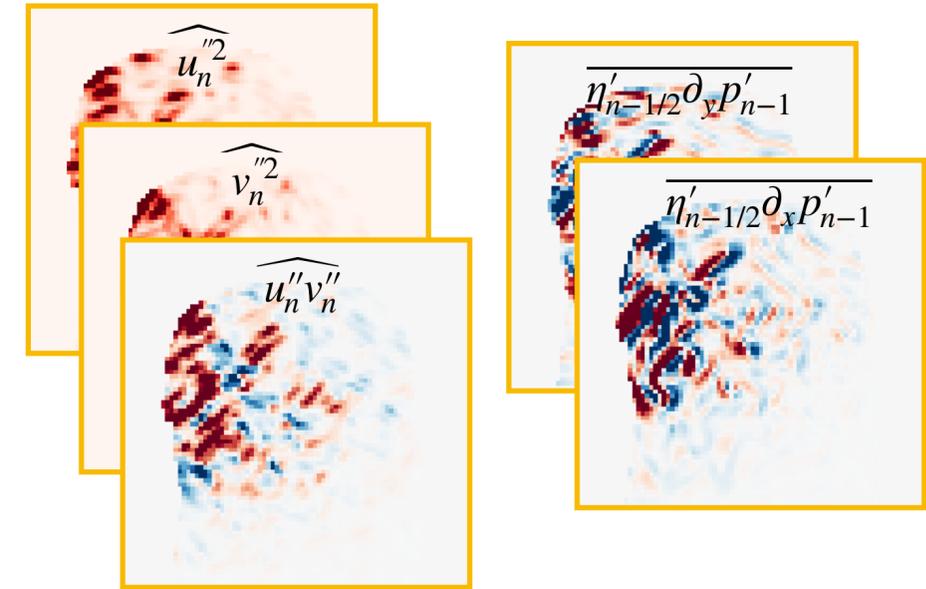
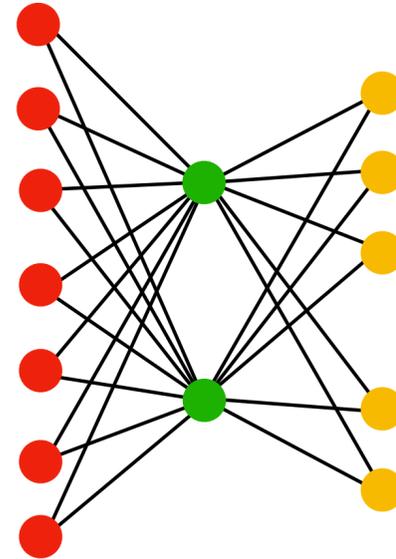
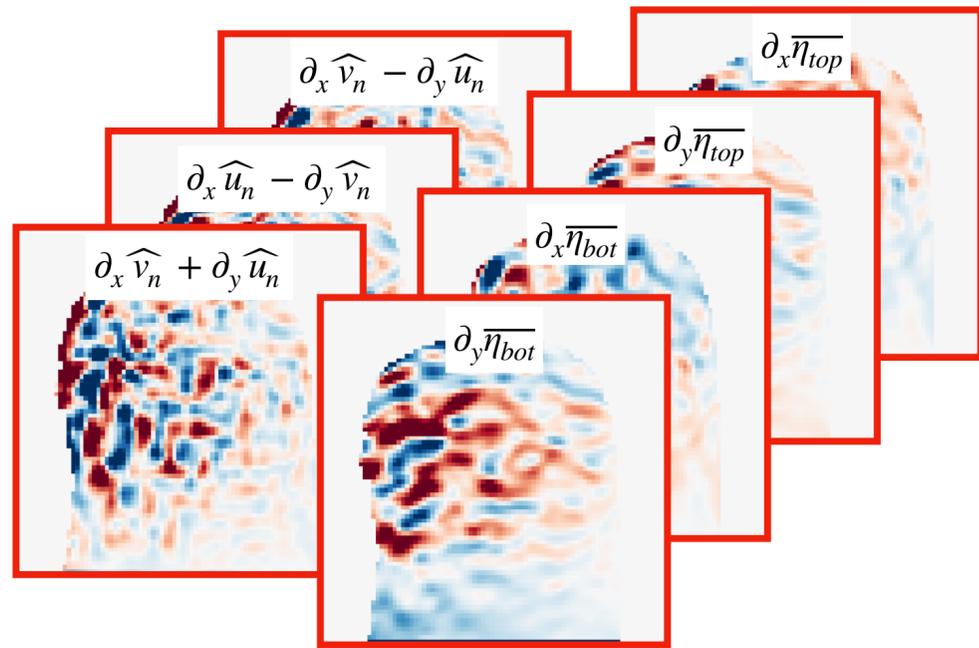


Thickness flux components

$$\Delta x^2 f ||\nabla u|| ||S|| \text{ANN} \left(\frac{||\nabla u||}{||S||}, \frac{S}{||S||} \right) \approx \widehat{E}_{thick}$$



Parameterisation Development: 5) Artificial Neural Network



Momentum flux components

$$\Delta x^2 ||\nabla u||^2 \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{mom}$$

$$\Delta^2 = 2 (\delta x \delta y)^2 / ((\delta x)^2 + (\delta y)^2)$$

Normalized inputs

ANN

Non-dimensional outputs

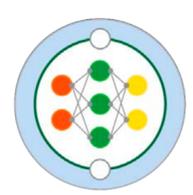
Momentum flux scaling

Thickness flux scaling

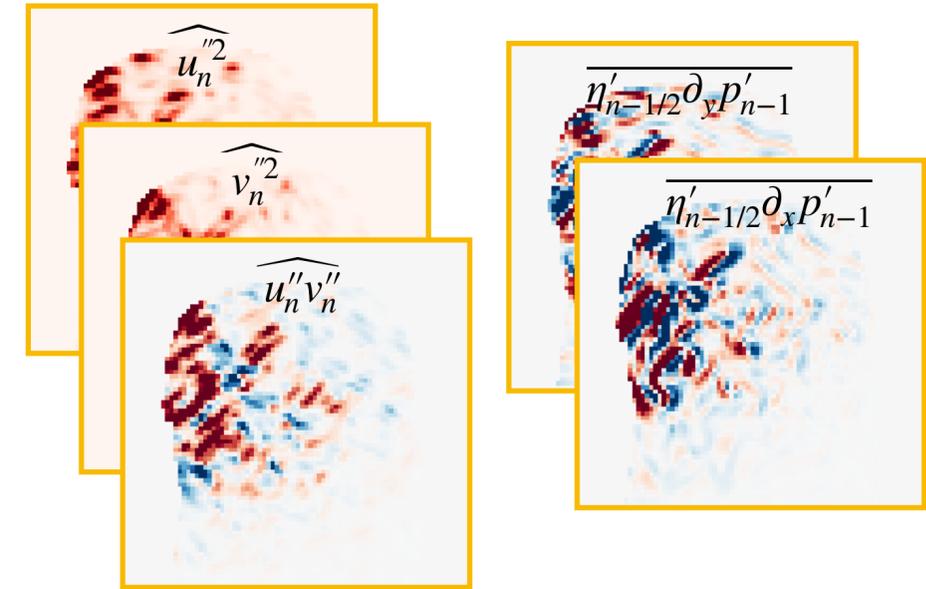
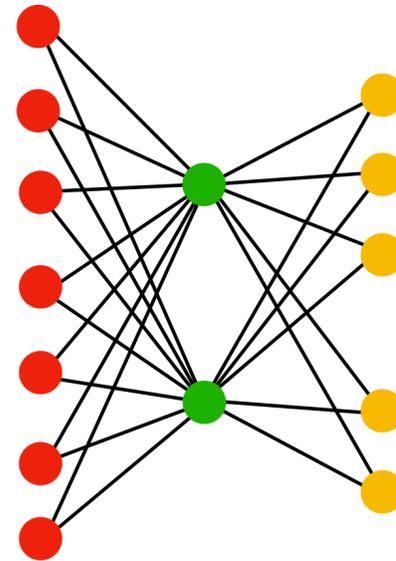
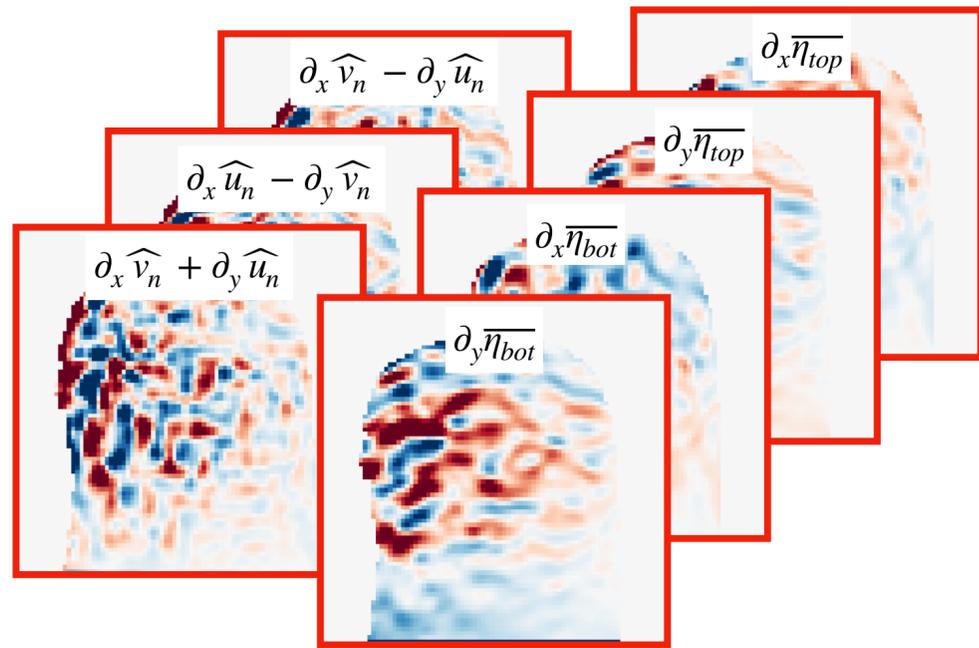
Thickness flux components

$$\Delta x^2 f ||\nabla u|| ||S|| \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{thick}$$

$$f = 2\Omega \sin \left(\frac{\pi \text{Latitude}}{180^\circ} \right)$$



Parameterisation Development: 5) Artificial Neural Network



Based off of eddy energy system

Momentum flux components

$$\Delta x^2 ||\nabla u||^2 \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{mom}$$

Thickness flux components

$$\Delta x^2 f ||\nabla u|| ||S|| \text{ANN} \left(\frac{\nabla u}{||\nabla u||}, \frac{S}{||S||} \right) \approx \widehat{E}_{thick}$$

Normalized inputs

ANN

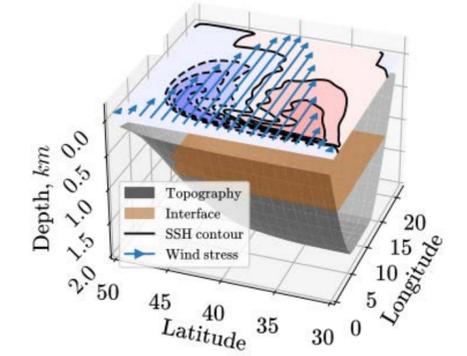
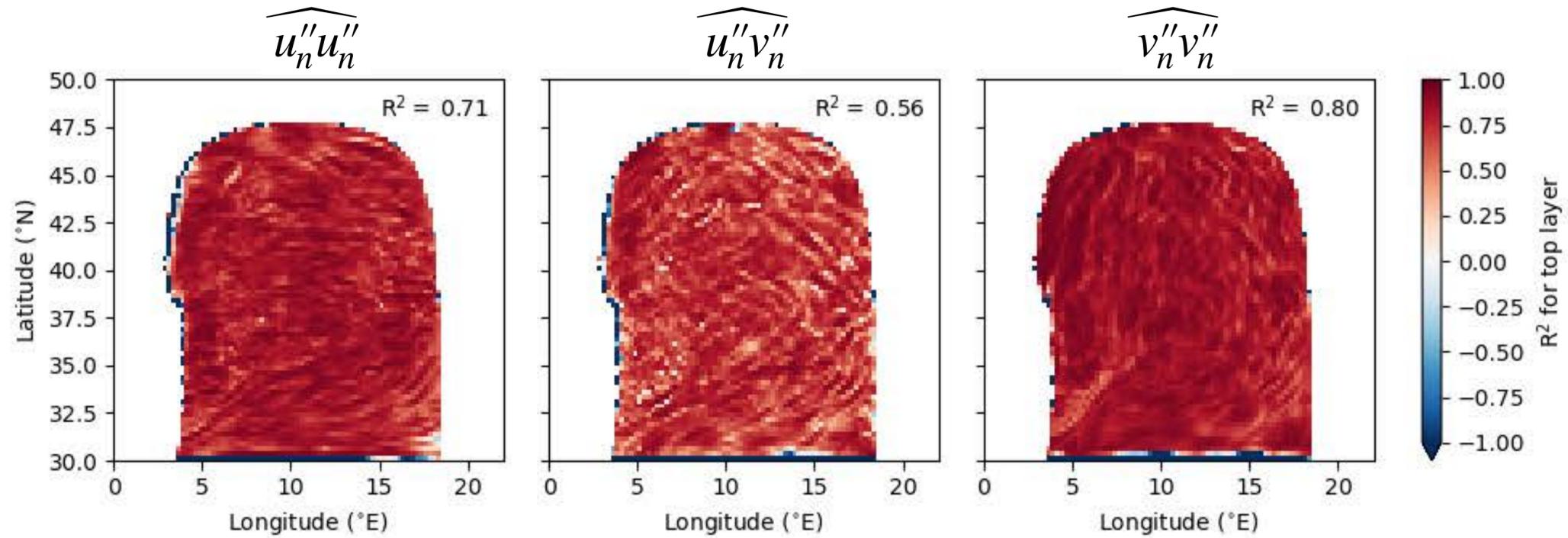
Non-dimensional outputs

Momentum flux scaling

Thickness flux scaling

EPF tensor

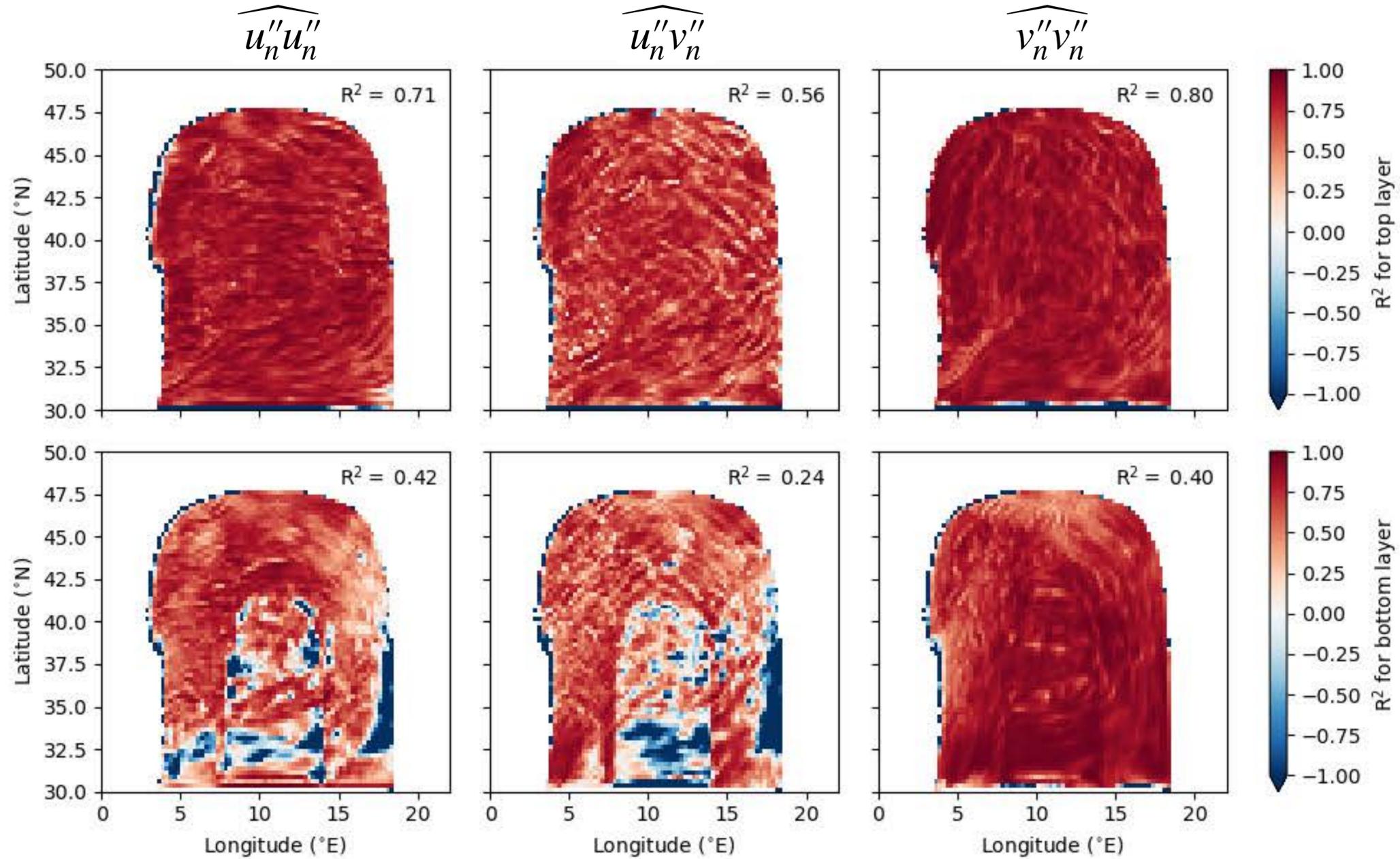
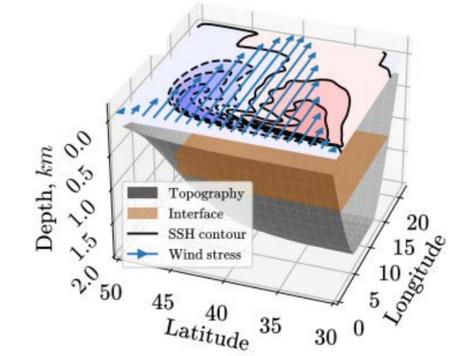
Offline performance on test data



High R^2 for Reynolds' stresses in top layer

*The R^2 is set to 0.0 when the spatial average $R^2 < 0$

Offline performance on test data



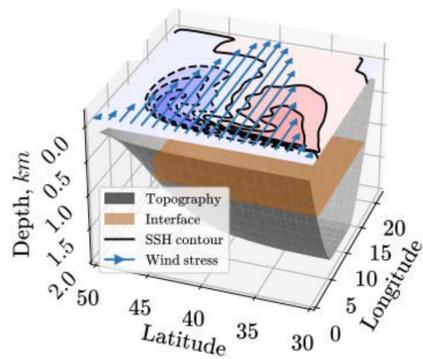
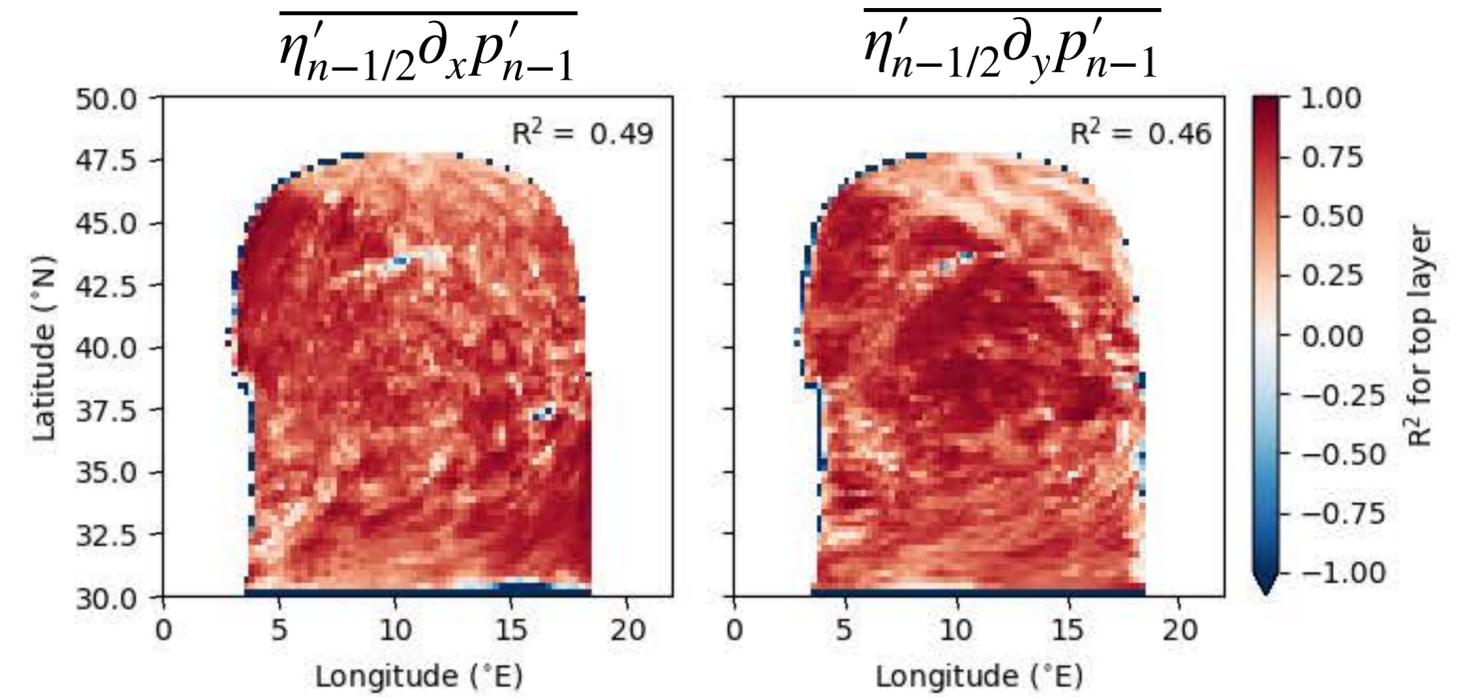
High R^2 for Reynolds' stresses in top layer

Worse performance in bottom layer

*The R^2 is set to 0.0 when the spatial average $R^2 < 0$

Offline performance on test data

Moderate R^2 for dual form stresses in top layer

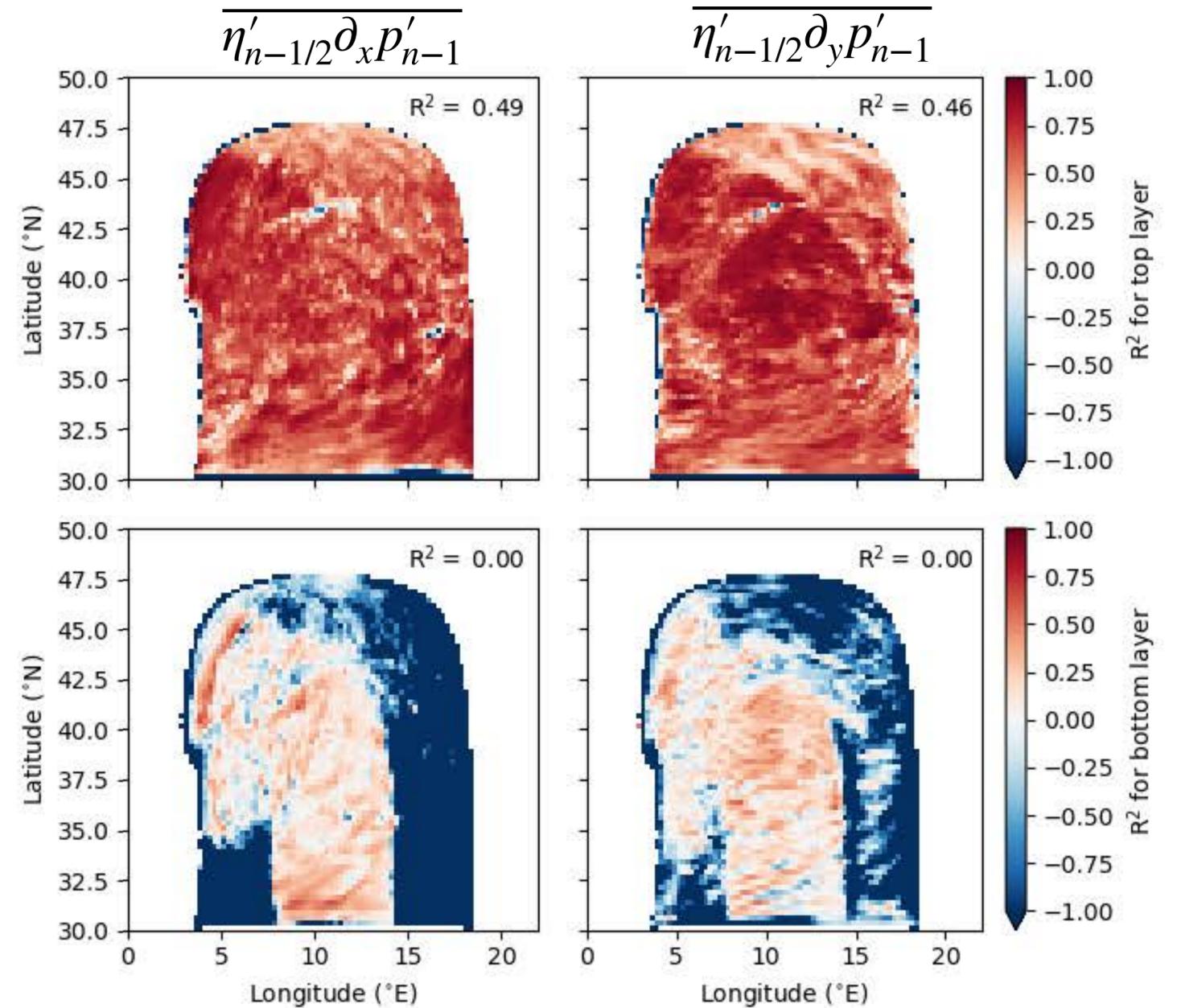
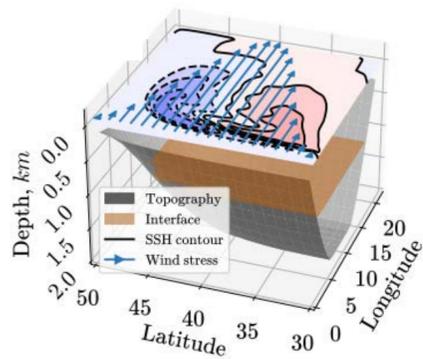


*The R^2 is set to 0.0 when the spatial average $R^2 < 0$

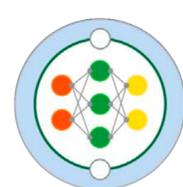
Offline performance on test data

Moderate R^2 for dual form stresses in top layer

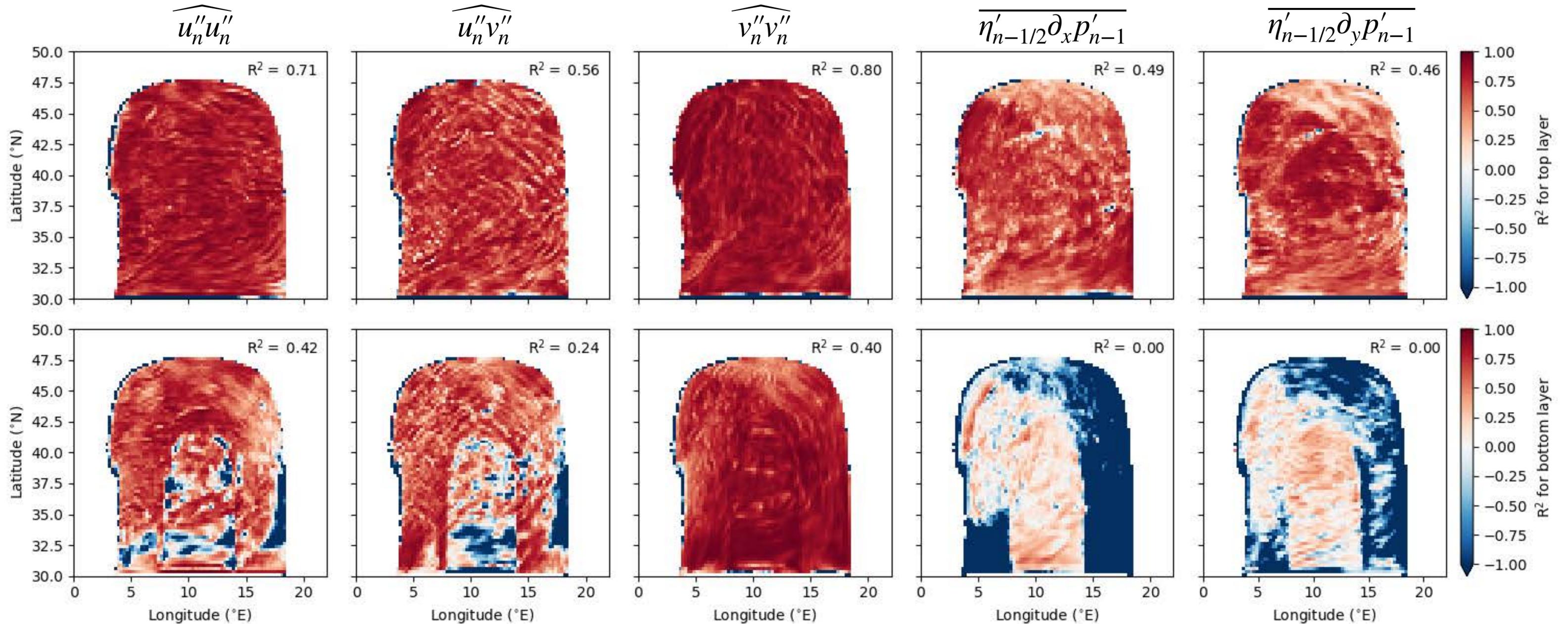
Poor R^2 for dual form stresses in bottom layer



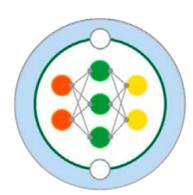
*The R^2 is set to 0.0 when the spatial average $R^2 < 0$



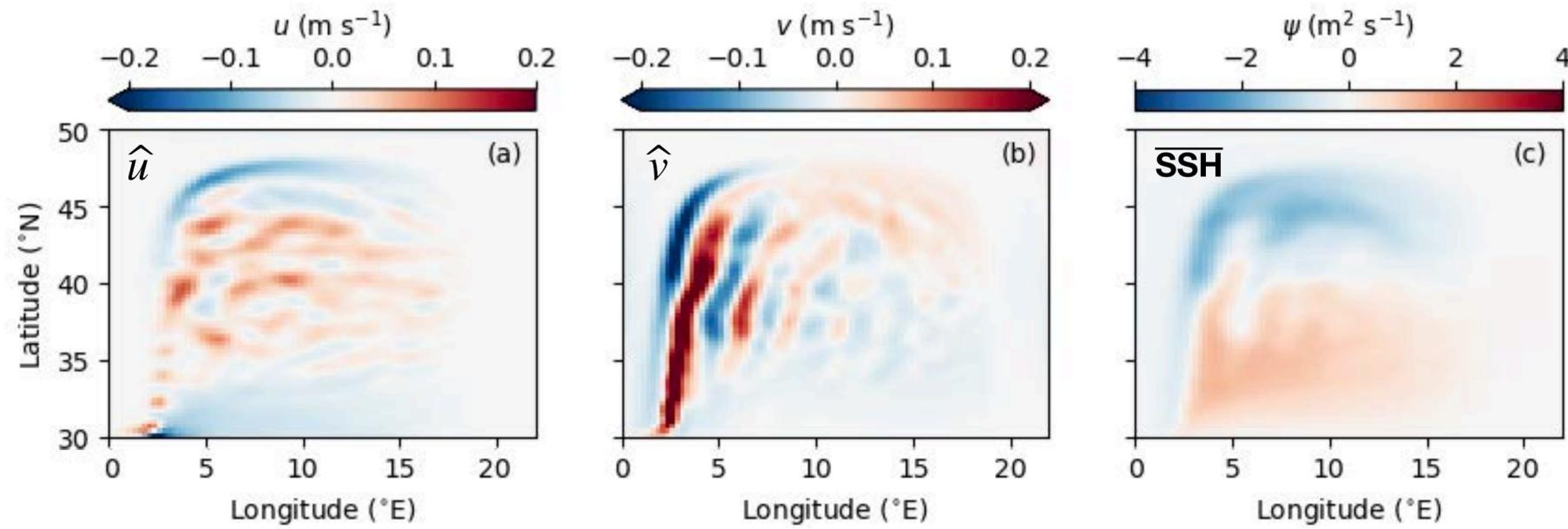
Offline performance on test data



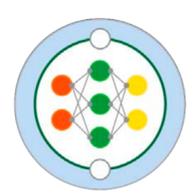
*The R^2 is set to 0.0 when the spatial average $R^2 < 0$



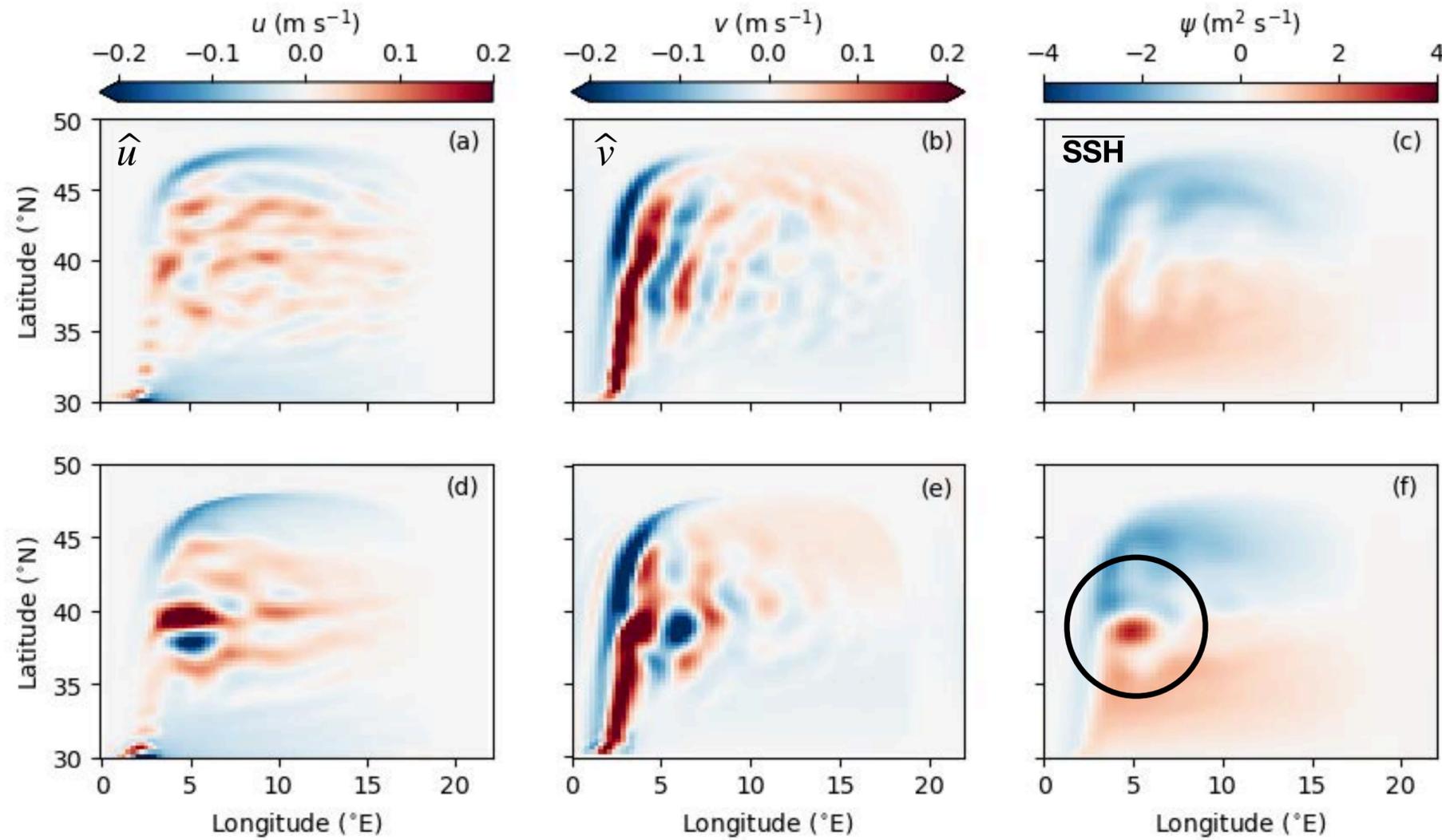
Online Implementation: Top Layer Mean Flow



1/32 $^{\circ}$ flow field filtered and coarsened to 1/4 $^{\circ}$ resolution.



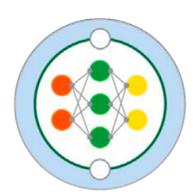
Online Implementation: Top Layer Mean Flow



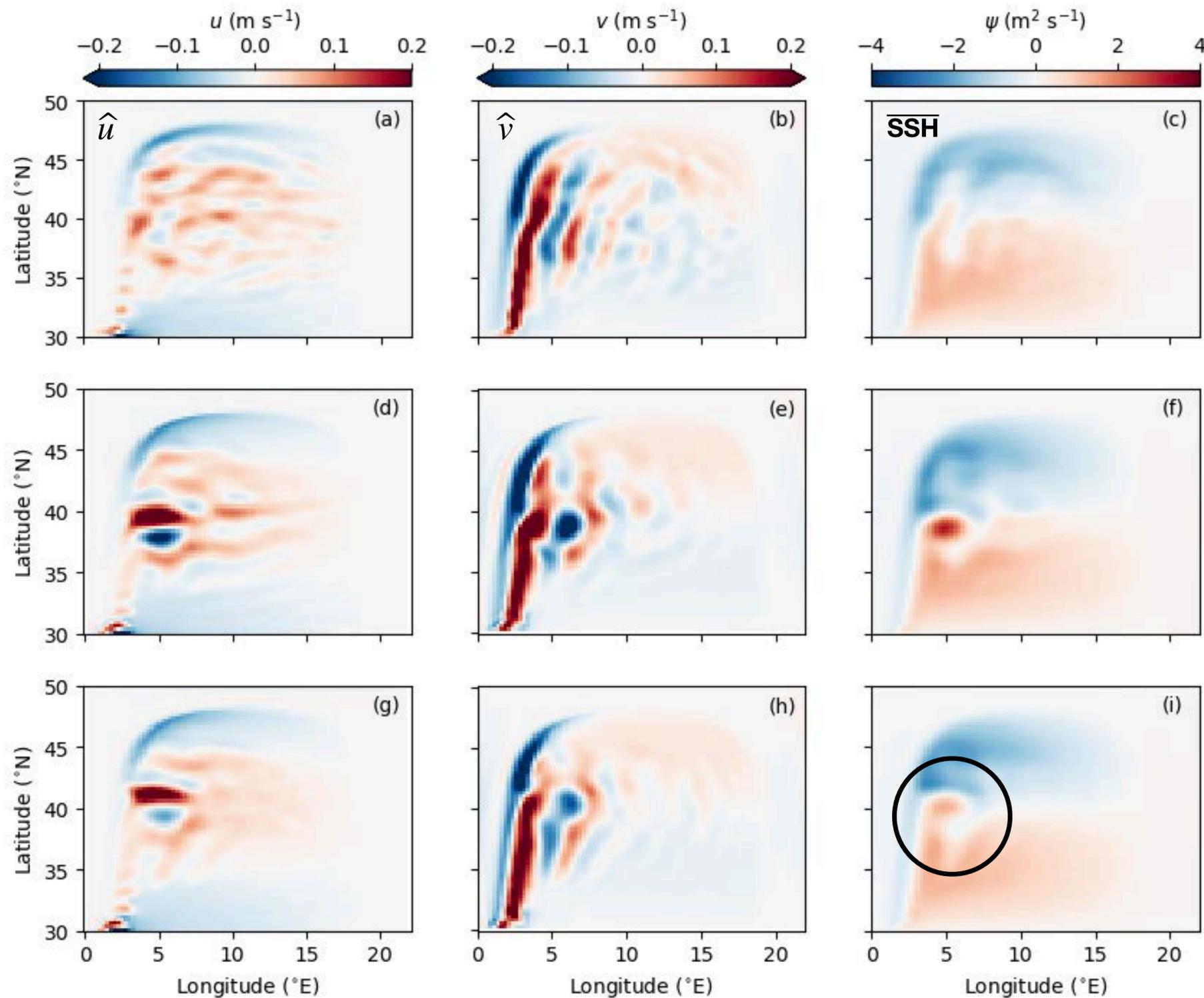
$1/32^\circ$ flow field filtered and coarsened to $1/4^\circ$ resolution.

$1/4^\circ$ resolution run with **no parameterisation** (only Smagorinsky)

Pesky persistent eddy



Online Implementation: Top Layer Mean Flow

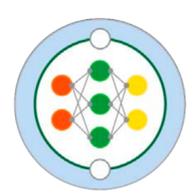


$1/32^{\circ}$ flow field filtered and coarsened to $1/4^{\circ}$ resolution.

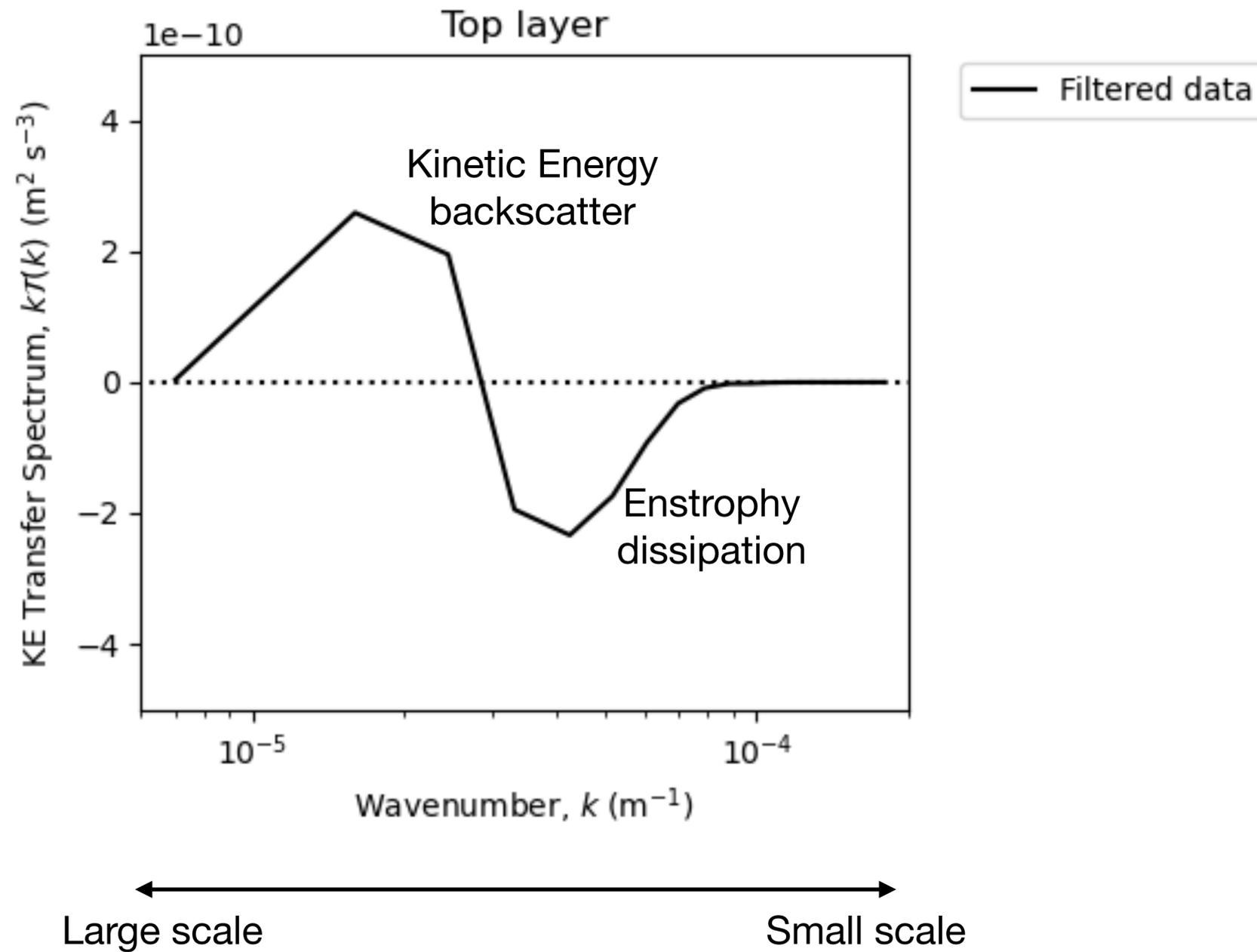
$1/4^{\circ}$ resolution run with **no parameterisation** (only Smagorinsky)

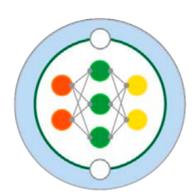
$1/4^{\circ}$ resolution run with **EPF ANN parameterisation** (in addition to Smagorinsky)

Pesky persistent eddy is **weakened by parameterisation!**

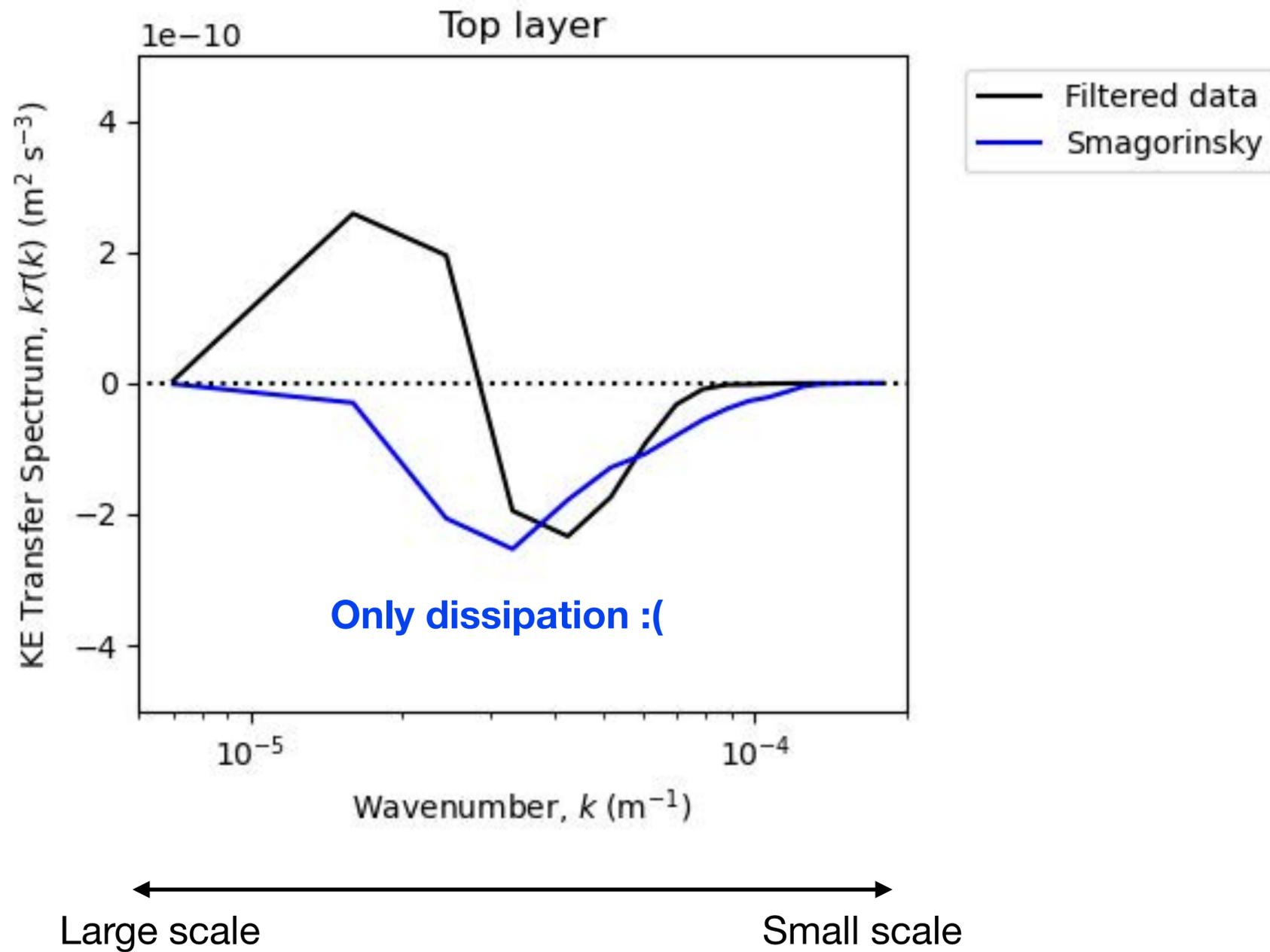


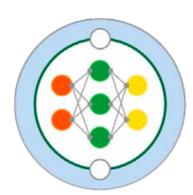
Isotropic KE transfer spectra



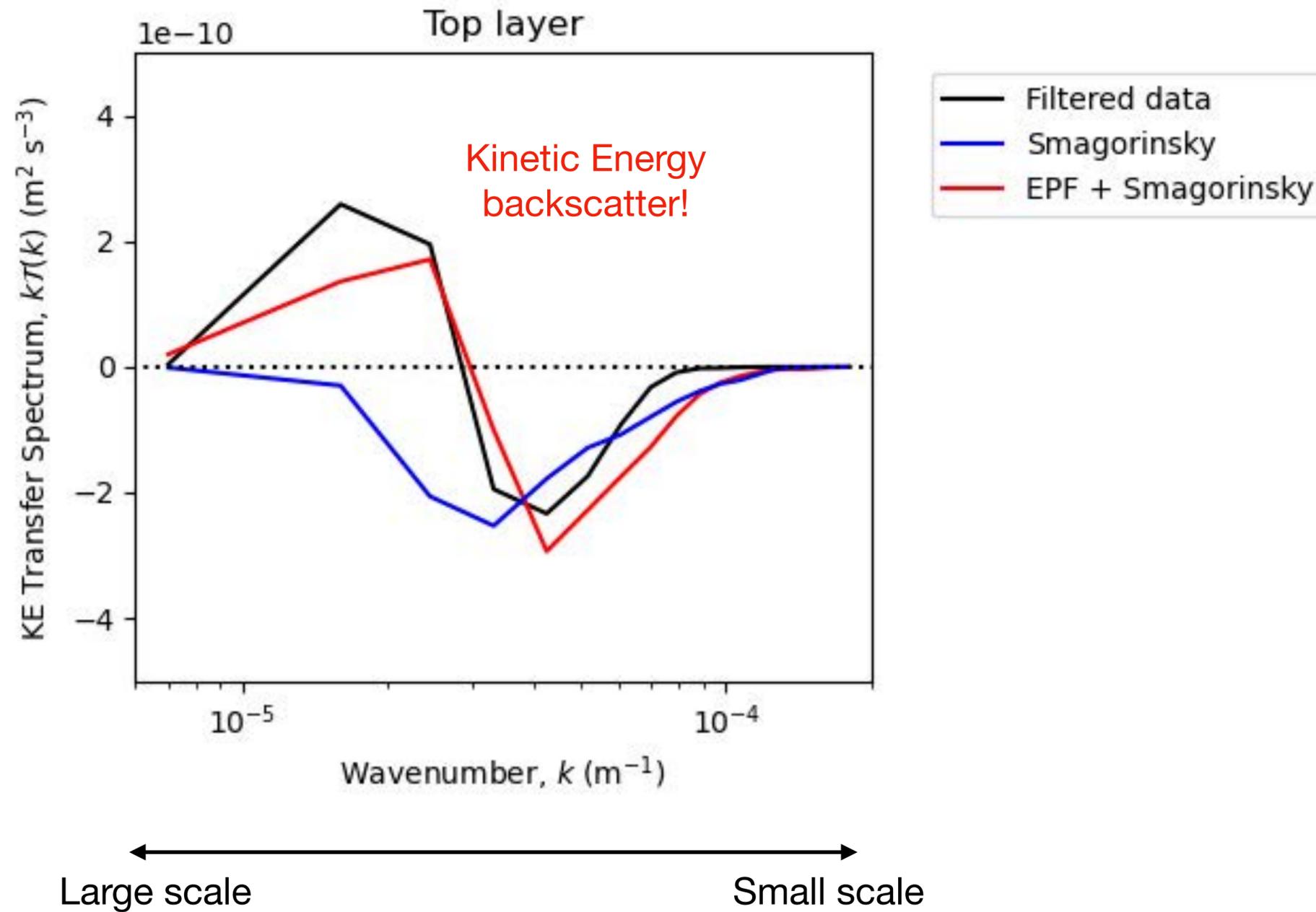


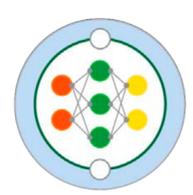
Isotropic Kinetic Energy transfer spectra



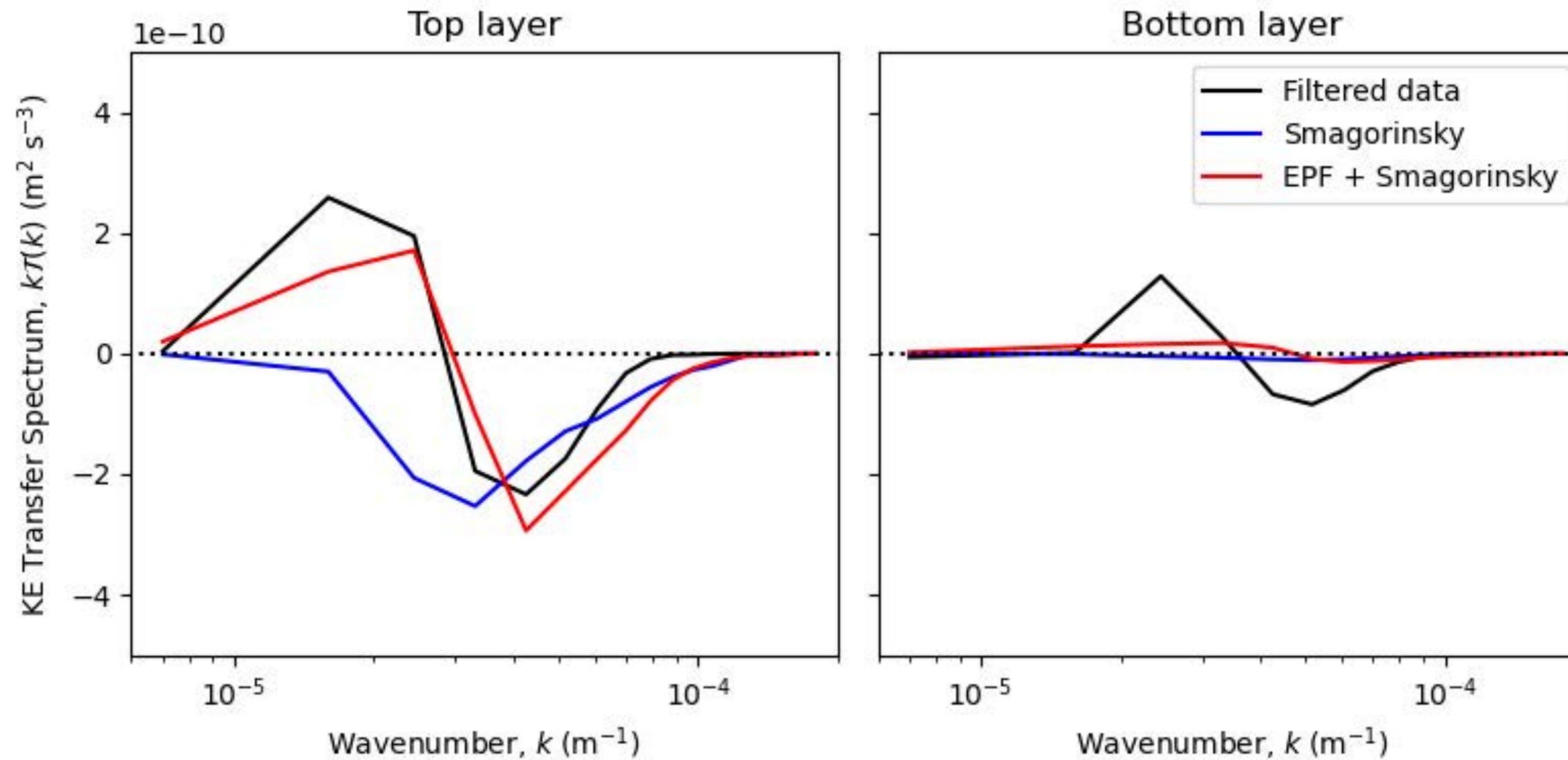


Isotropic Kinetic Energy transfer spectra

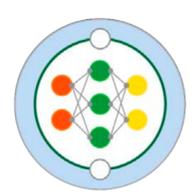




Isotropic Kinetic Energy transfer spectra



Not much improvement in bottom layer



Concluding remarks

Initial data-driven parametrization to capture the mesoscale energy cycle using the Eliassen-Palm Flux tensor components:

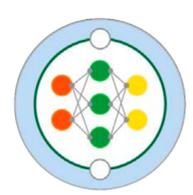
Idealised runs, double gyre

- **Offline performance:**
 - Room for improvement in training (more epochs, more data, regularization techniques, etc)
 - ... however, improvements offline do not guarantee improvements online
- **Online performance:**
 - Doesn't blow up!
 - Weakens pesky persistent eddy in mean flow
 - Better representation of energy spectral transfer
 - Still room for improvement

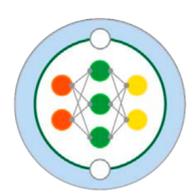
Upcoming:

- **How can we improve representation of thickness fluxes?**
 - Improve ANN to be implemented

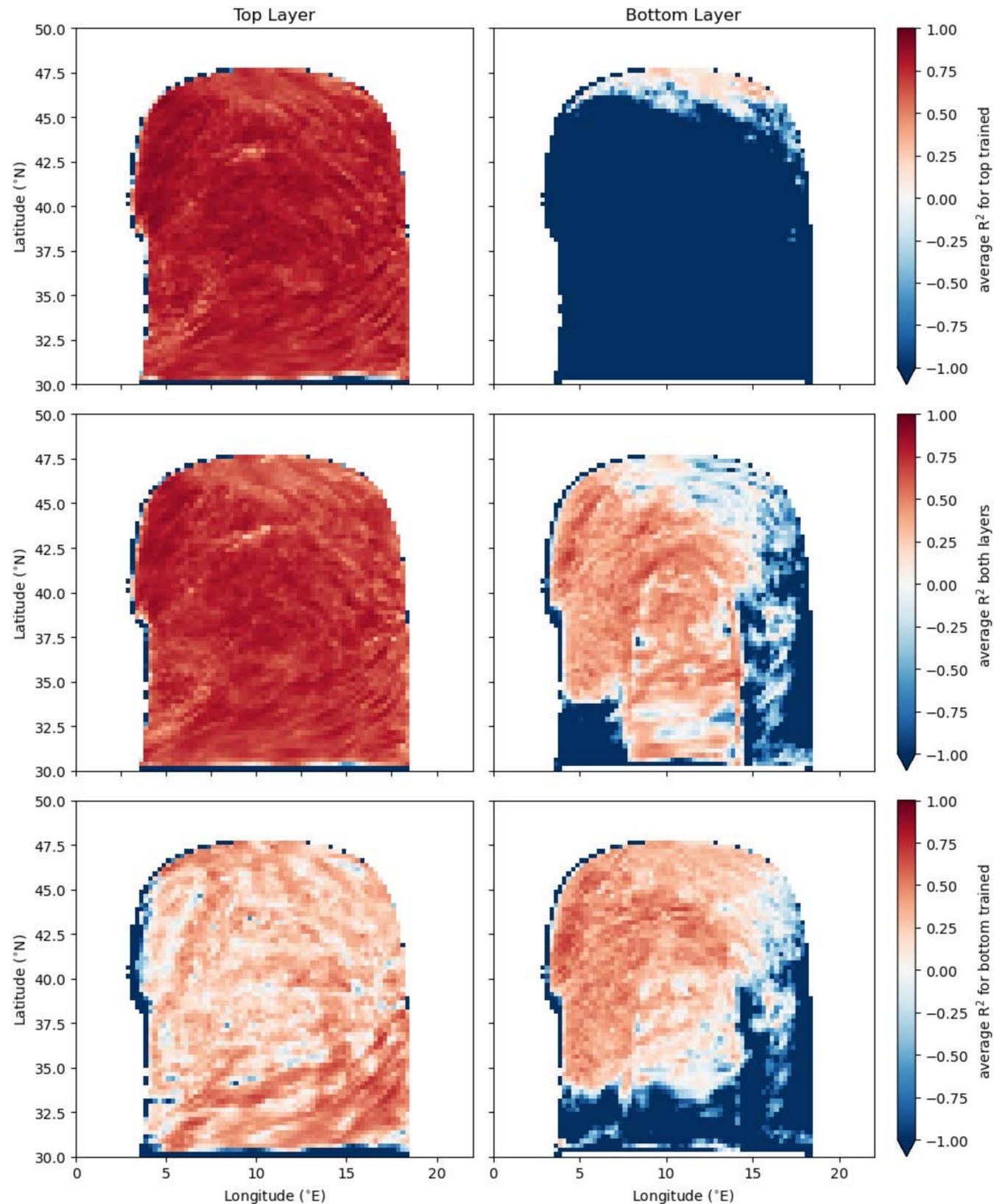
Use of eddy energy system to produce a single parameterisation that captures both momentum and thickness fluxes seems promising 😊



Supplementary Slides



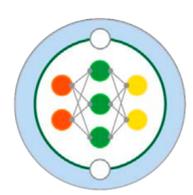
Supplementary Slide: Weighting layer influence during training



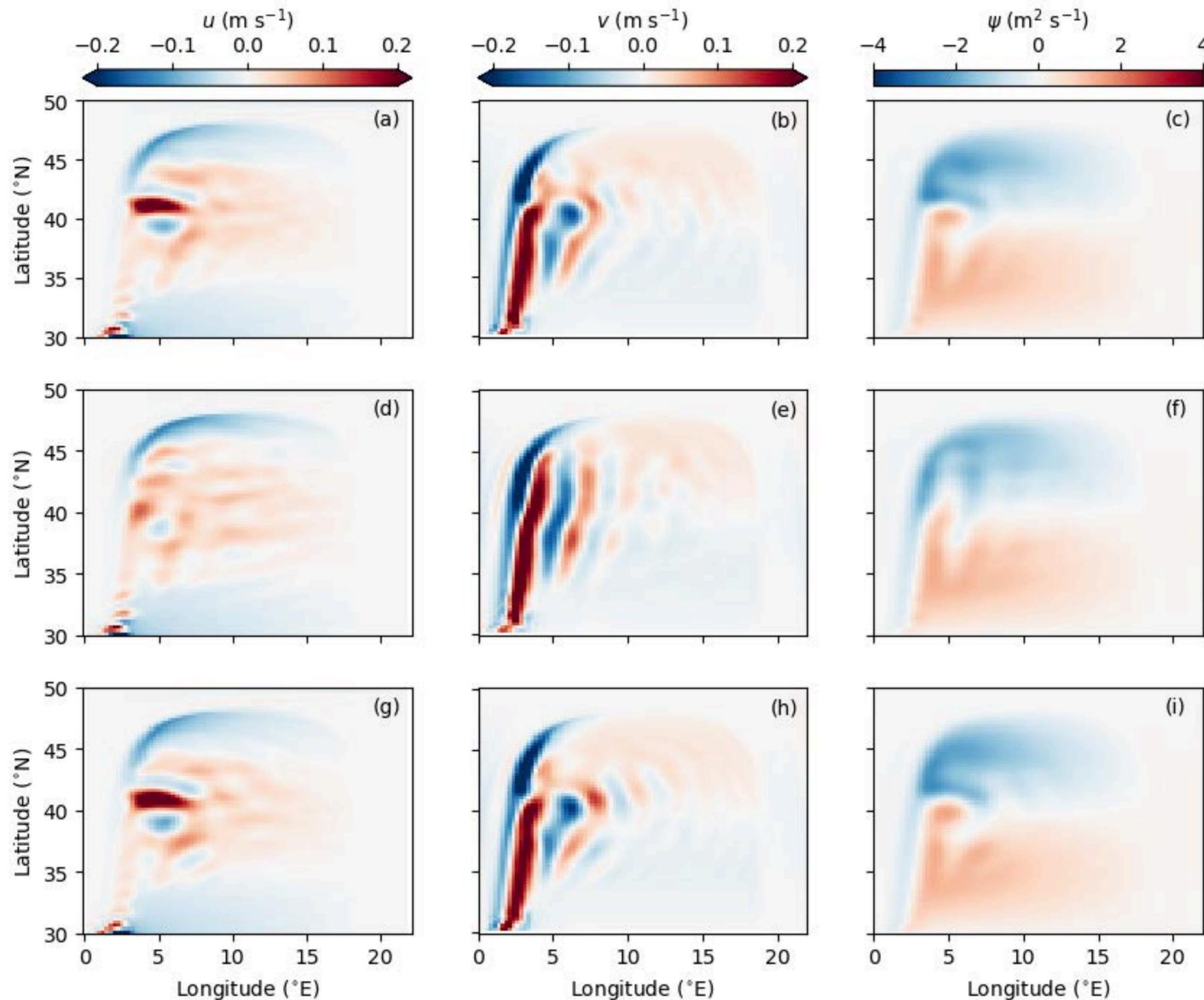
Alternate ANN trained, where back-propagated loss depends **only** on the **top layer**

‘Original’ ANN trained, where back-propagated loss depends **equally** on **top and bottom layer**

Alternate ANN trained, where back-propagated loss depends **only** on the **bottom layer**



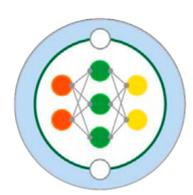
Supplementary Slide: **EPF parameterization contributions** for top layer



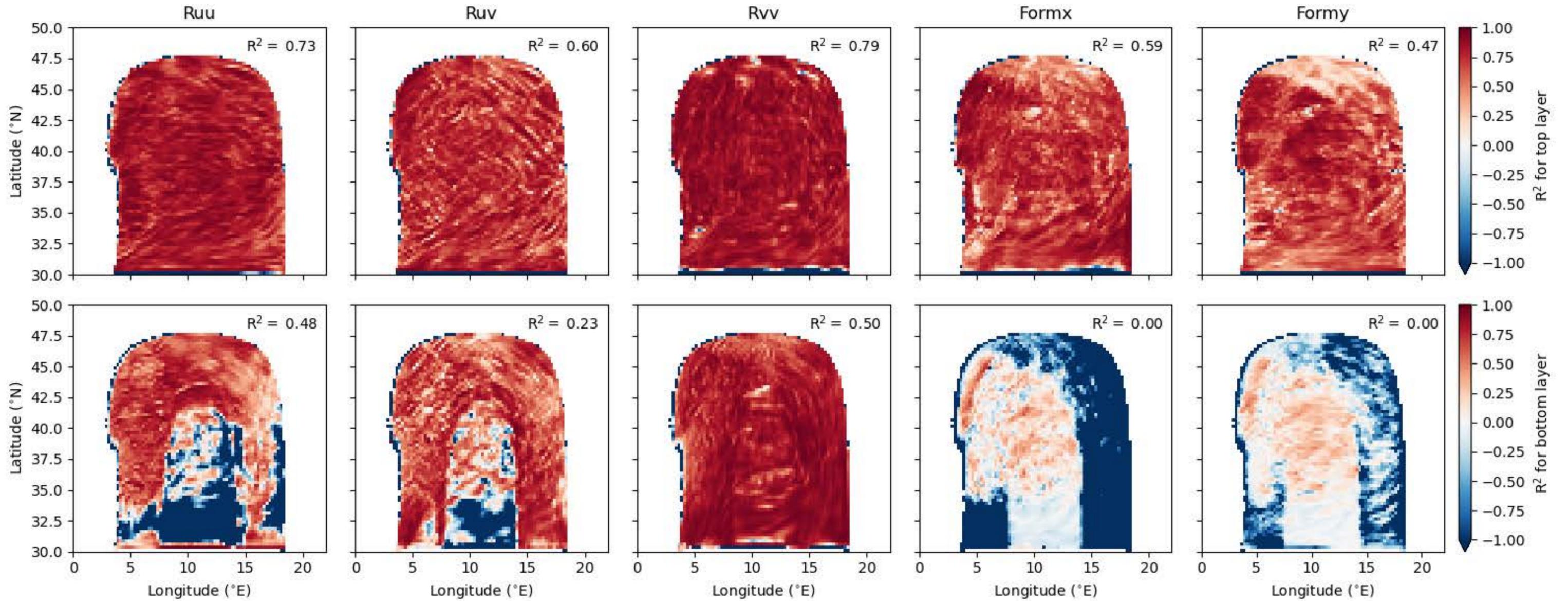
1/4° resolution DG run with **full EPF ANN parameterisation** (in addition to Smagorinsky)

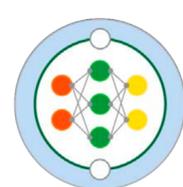
1/4° resolution DG run with **horizontal divergence of EPF** (in addition to Smagorinsky)

1/4° resolution DG run with **vertical divergence of EPF** (in addition to Smagorinsky)

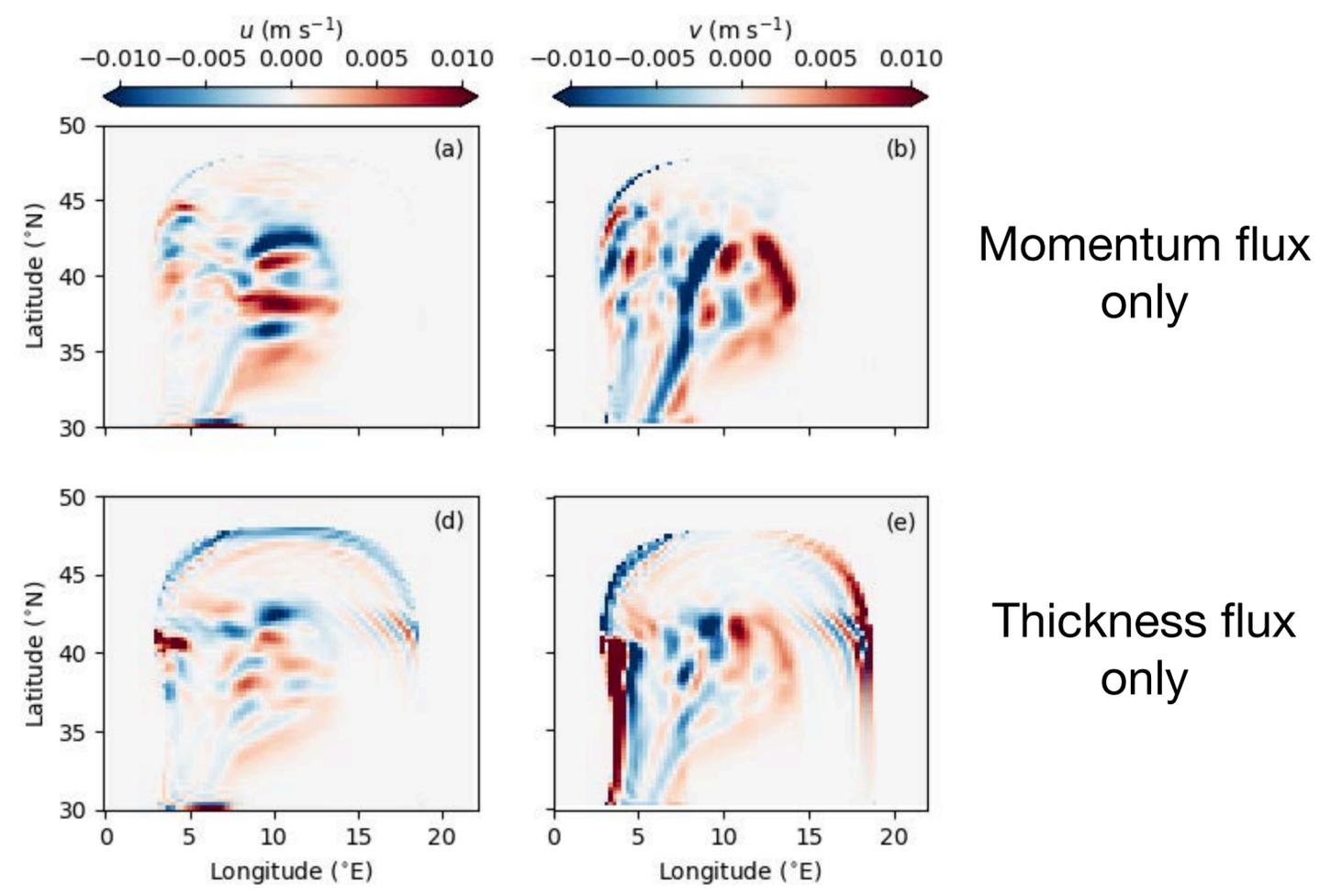
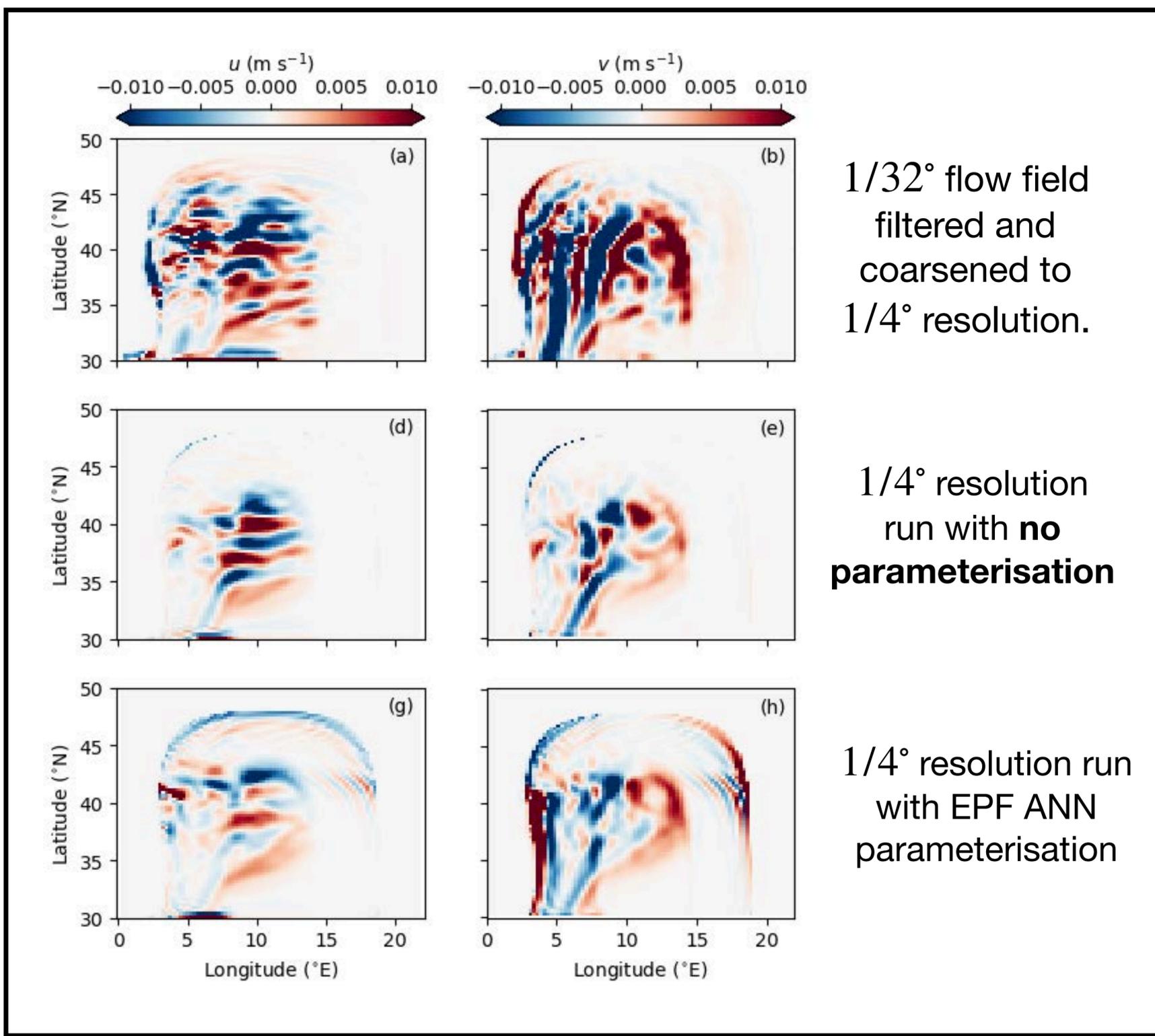


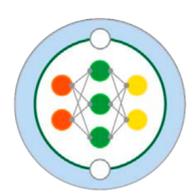
Supplementary Slide: ANN with bottom topography ignored





Large-scale flow field: Bottom layer





Strength of Parameterisation

Does increasing the strength of the acceleration due to the parameterisation improve representation of the mean flow?

